

Noise-assisted digital quantum simulation of open systems

José D. Guimarães, James Lim, Mikhail I. Vasilevskiy, Susana F. Huelga, Martin B. Plenio | 2022



Overview - Part I

- Use the intrinsic noise of NISQ devices as a resource for quantum computation.

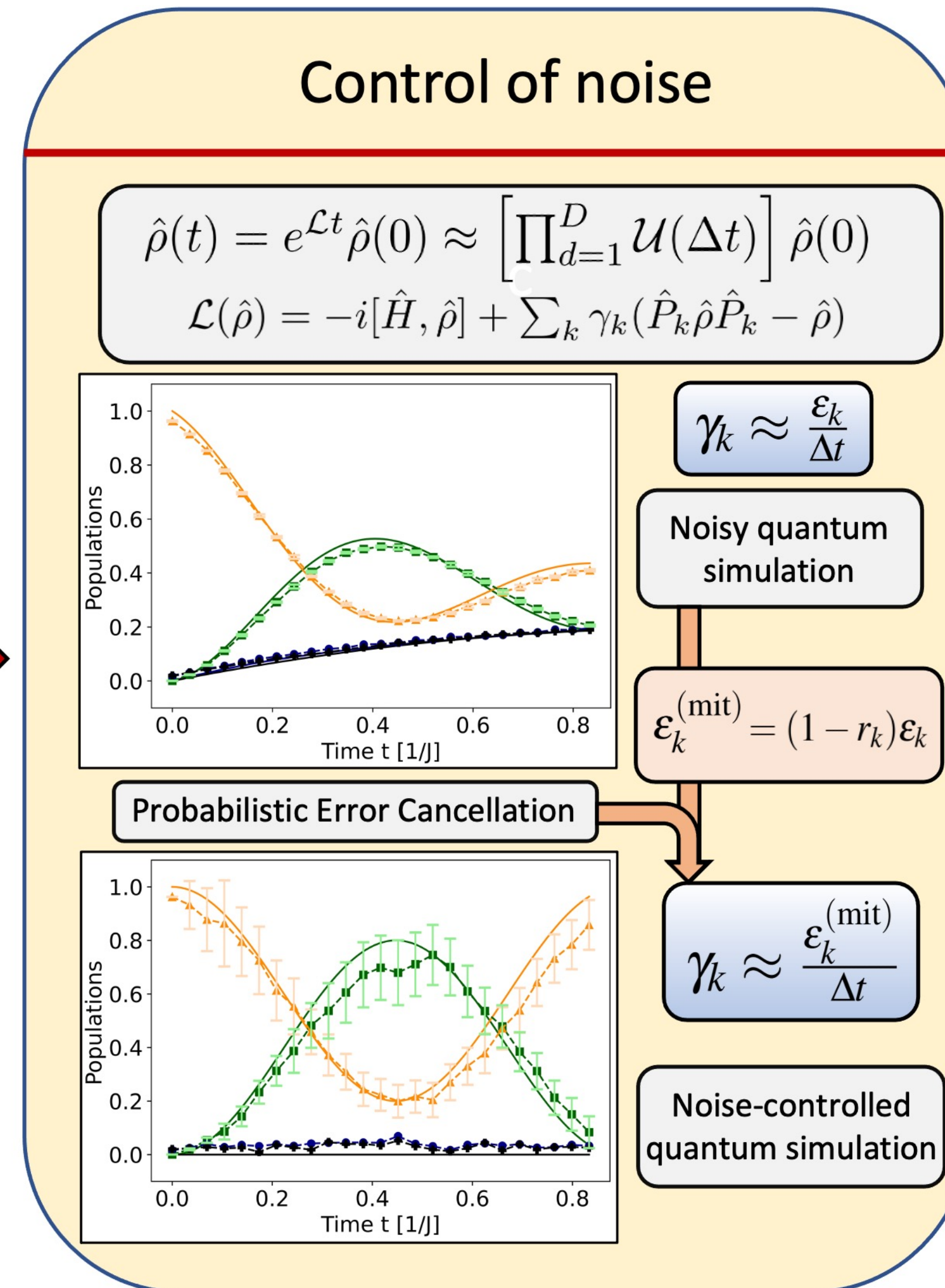
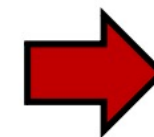
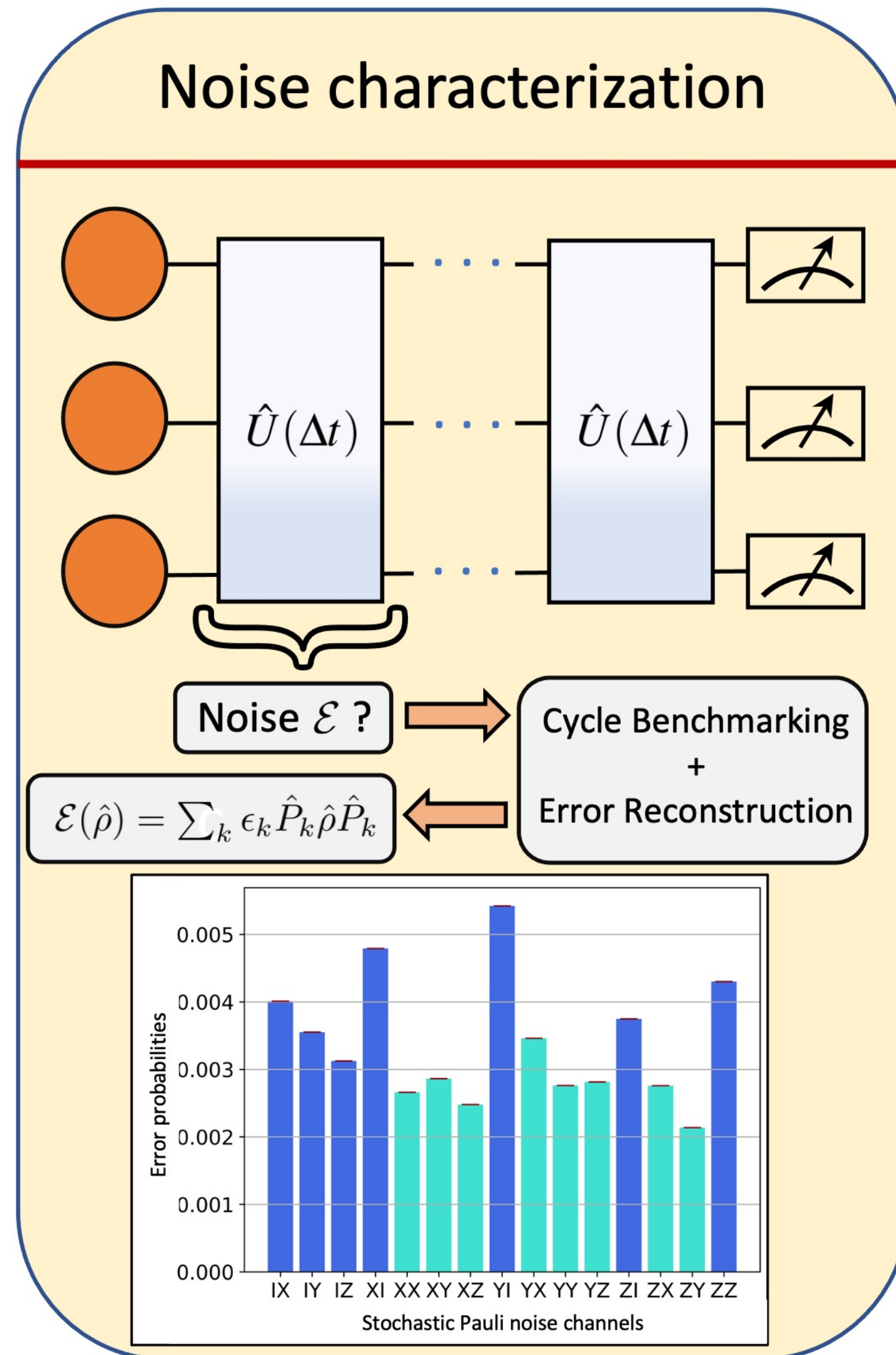
Overview - Part I

- Use the intrinsic noise of NISQ devices as a resource for quantum computation.
- Quantum simulation of Markovian dynamics of open quantum systems;

Overview - Part I

- Use the intrinsic noise of NISQ devices as a resource for quantum computation.
- Quantum simulation of Markovian dynamics of open quantum systems;
- The quantum hardware does not need to be changed in order to tune the decoherence rates;

Overview - Part II



Time-evolution via product formulas

- Time-evolution in the quantum computer,

Noiseless quantum computer: $e^{-i\hat{H}t} |\Psi(0)\rangle \approx \prod_{d=1}^D \hat{U}_k(\Delta t) |\Psi(0)\rangle, \quad \hat{U}_1(\Delta t) = \prod_{j=1}^N e^{-i\hat{H}_j \Delta t}, \quad \Delta t = t/D.$

$$\hat{H} = \sum_{j=1}^N \hat{H}_j, \quad \hat{H}_j = \alpha_j \hat{P}_j$$

Time-evolution via product formulas

- Time-evolution in the quantum computer,

Noiseless quantum computer:
$$e^{-i\hat{H}t} |\Psi(0)\rangle \approx \prod_{d=1}^D \hat{U}_k(\Delta t) |\Psi(0)\rangle, \quad \hat{U}_1(\Delta t) = \prod_{j=1}^N e^{-i\hat{H}_j \Delta t}, \quad \Delta t = t/D.$$

Noisy quantum computer:
$$\frac{d\hat{\rho}(t)}{dt} = \mathcal{L}[\hat{\rho}(t)] = -i[\hat{H}, \hat{\rho}(t)] + \mathcal{D}_{\text{intrinsic}}[\hat{\rho}(t)]$$

- Markovian noise.
- Weak noise over a Trotter iteration.

Noise characterization

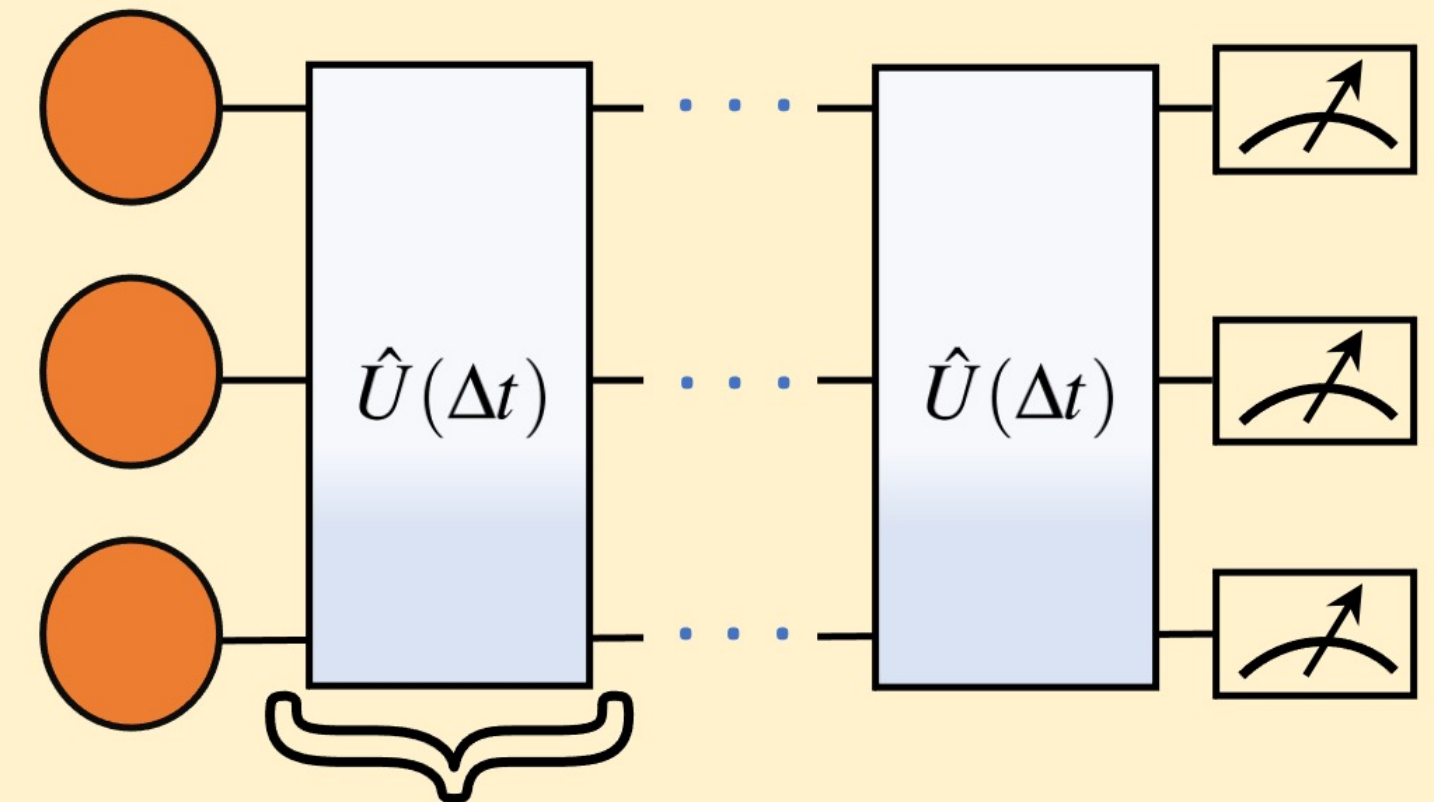
CB + ER

Erhard, Alexander, et al. *Nature communications* 10.1 (2019): 1-7.

Flammia, Steven T., and Joel J. Wallman. *ACM Transactions on Quantum Computing* 1.1 (2020): 1-32.

K-qubit stochastic Pauli channel: $\mathcal{E}(\rho) = \sum_k \epsilon_k \hat{P}_k \rho \hat{P}_k$

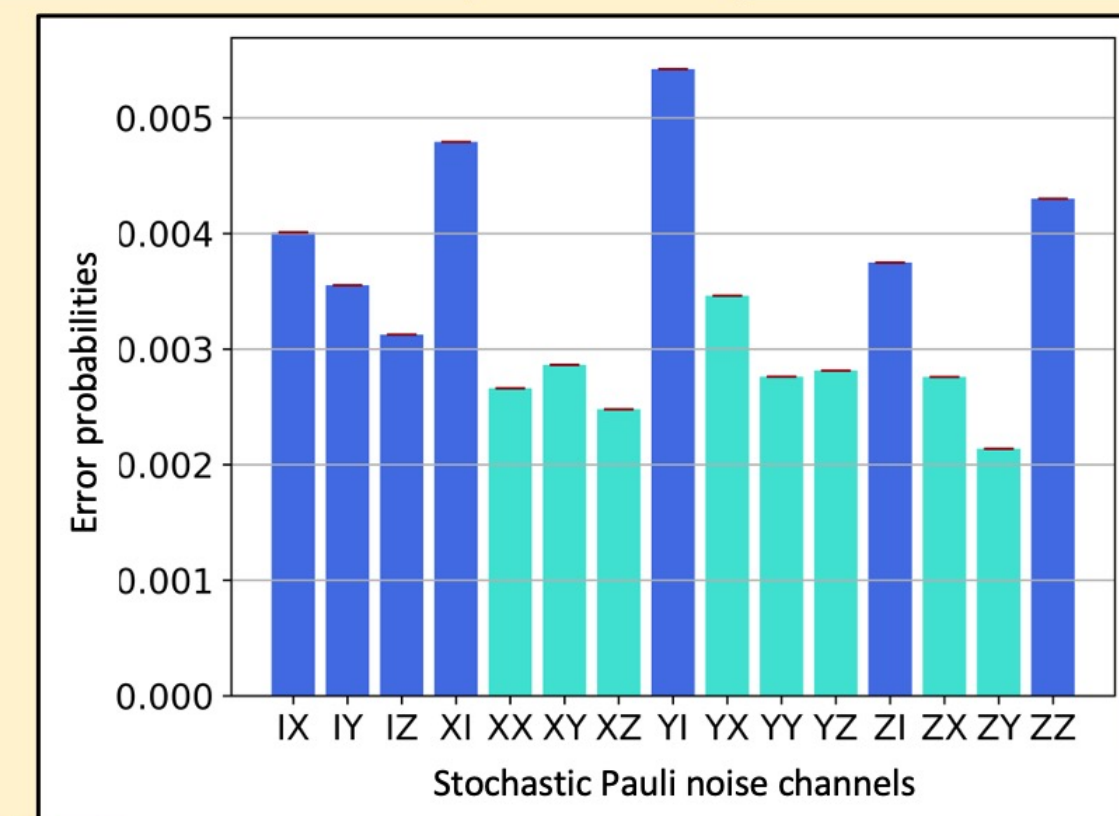
Noise characterization



Noise \mathcal{E} ?

Cycle Benchmarking
+
Error Reconstruction

$$\mathcal{E}(\hat{\rho}) = \sum_k \epsilon_k \hat{P}_k \hat{\rho} \hat{P}_k$$



Noise characterization

CB + ER

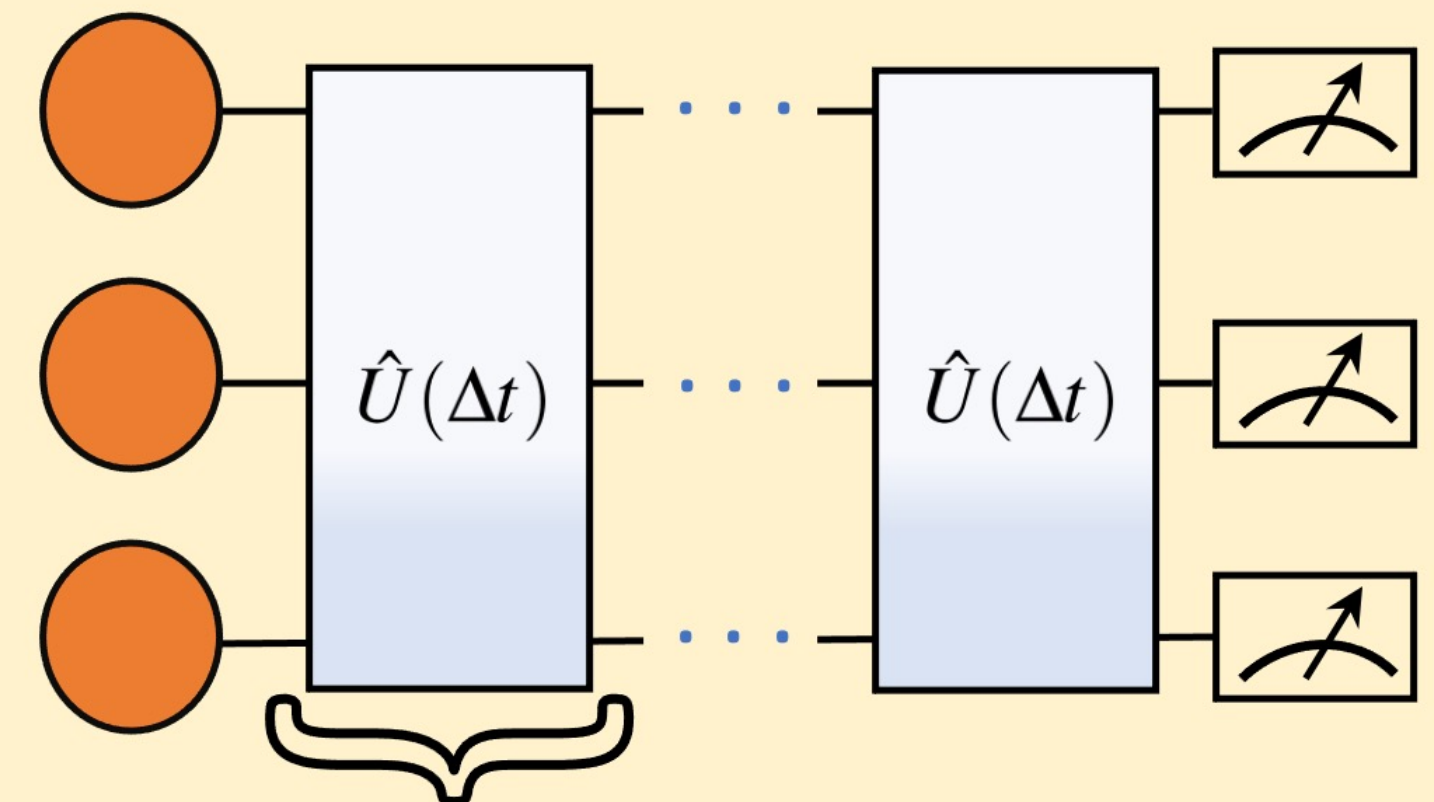
K-qubit stochastic Pauli channel: $\mathcal{E}(\rho) = \sum_k \epsilon_k \hat{P}_k \rho \hat{P}_k$

$$K=1: \mathcal{E}_m^{(1)}(\hat{\rho}) = \epsilon_0 \hat{\rho} + \epsilon_X \hat{X}_m \hat{\rho} \hat{X}_m + \epsilon_Y \hat{Y}_m \hat{\rho} \hat{Y}_m + \epsilon_Z \hat{Z}_m \hat{\rho} \hat{Z}_m$$

$$K=2: \mathcal{E}_{m,m+1}^{(2)}(\hat{\rho}) = \mathcal{E}_m^{(1)}(\hat{\rho}) + \mathcal{E}_{m+1}^{(1)}(\hat{\rho})$$

$$+ \epsilon_{XX} \hat{X}_m \hat{X}_{m+1} \hat{\rho} \hat{X}_m \hat{X}_{m+1} + \epsilon_{XY} \hat{X}_m \hat{Y}_{m+1} \hat{\rho} \hat{X}_m \hat{Y}_{m+1} + \dots$$

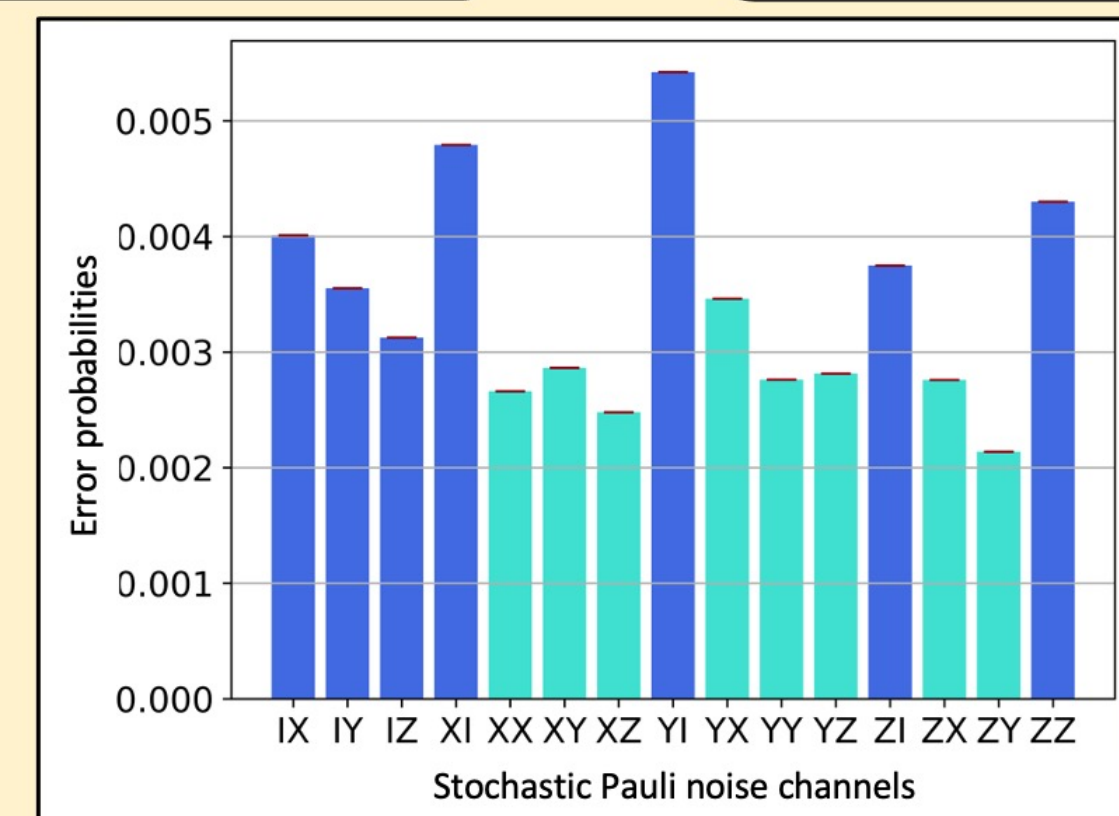
Noise characterization



Noise \mathcal{E} ?

Cycle Benchmarking
+
Error Reconstruction

$$\mathcal{E}(\hat{\rho}) = \sum_k \epsilon_k \hat{P}_k \hat{\rho} \hat{P}_k$$



Noise characterization

CB + ER

K-qubit stochastic Pauli channel: $\mathcal{E}(\rho) = \sum_k \epsilon_k \hat{P}_k \rho \hat{P}_k$

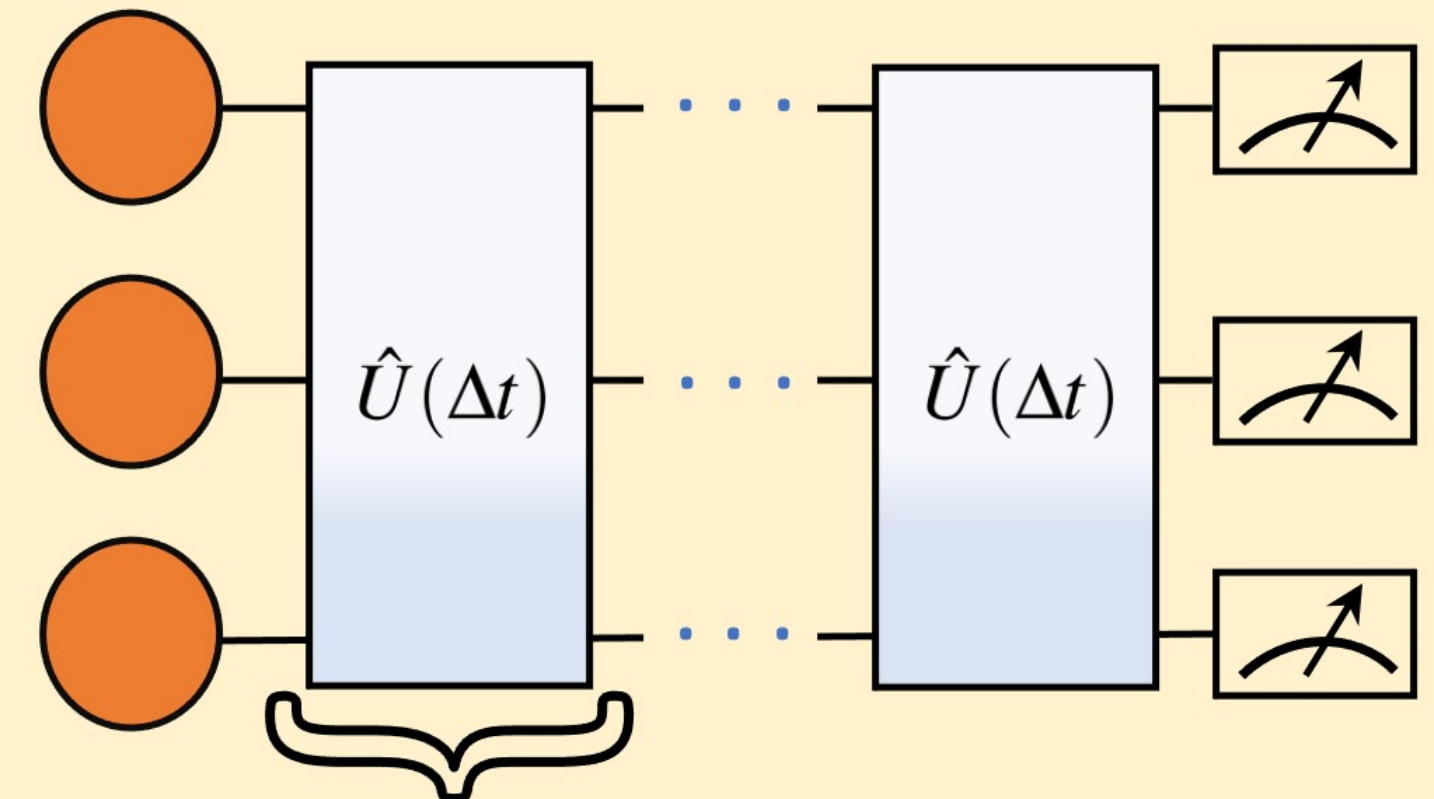
$$K=1: \mathcal{E}_m^{(1)}(\hat{\rho}) = \epsilon_0 \hat{\rho} + \epsilon_X \hat{X}_m \hat{\rho} \hat{X}_m + \epsilon_Y \hat{Y}_m \hat{\rho} \hat{Y}_m + \epsilon_Z \hat{Z}_m \hat{\rho} \hat{Z}_m$$

$$K=2: \mathcal{E}_{m,m+1}^{(2)}(\hat{\rho}) = \mathcal{E}_m^{(1)}(\hat{\rho}) + \mathcal{E}_{m+1}^{(1)}(\hat{\rho})$$

$$+ \epsilon_{XX} \hat{X}_m \hat{X}_{m+1} \hat{\rho} \hat{X}_m \hat{X}_{m+1}, + \epsilon_{XY} \hat{X}_m \hat{Y}_{m+1} \hat{\rho} \hat{X}_m \hat{Y}_{m+1} + \dots$$

No need to characterize errors acting on more than K=2 nearest-neighbour qubits.

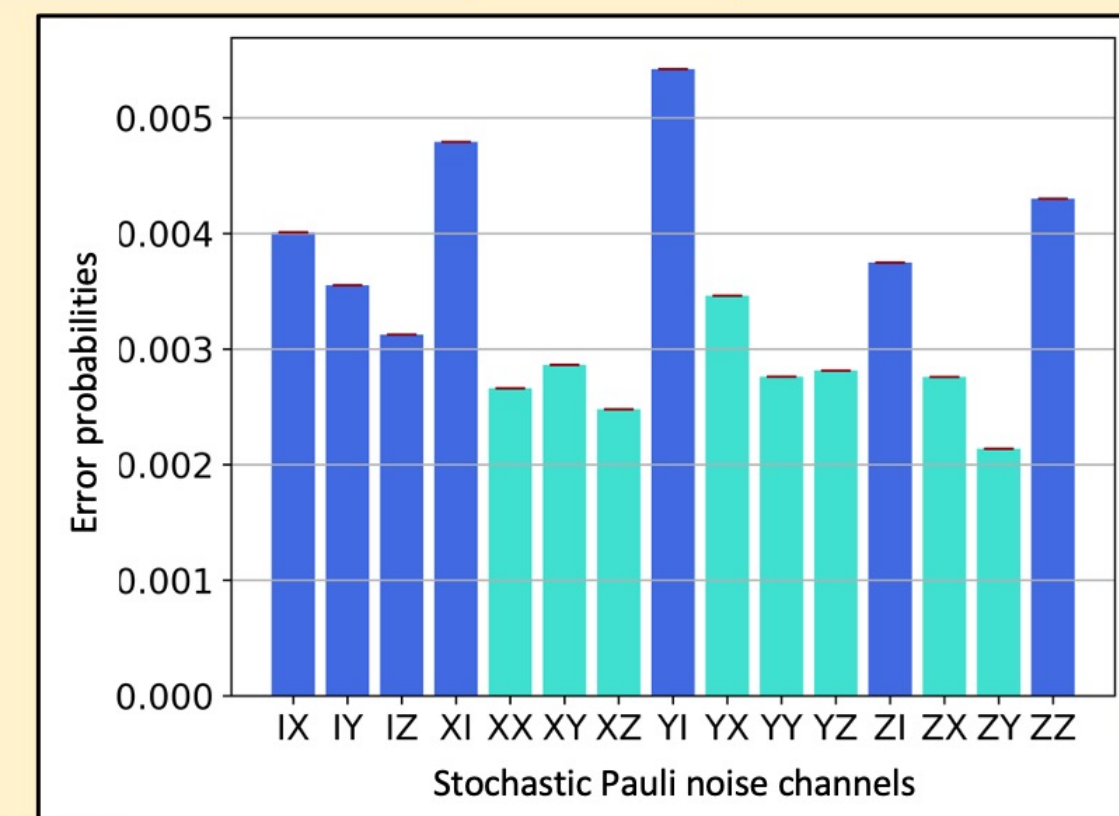
Noise characterization



Noise \mathcal{E} ?

Cycle Benchmarking
+
Error Reconstruction

$$\mathcal{E}(\hat{\rho}) = \sum_k \epsilon_k \hat{P}_k \hat{\rho} \hat{P}_k$$



Noise characterization

CB + ER

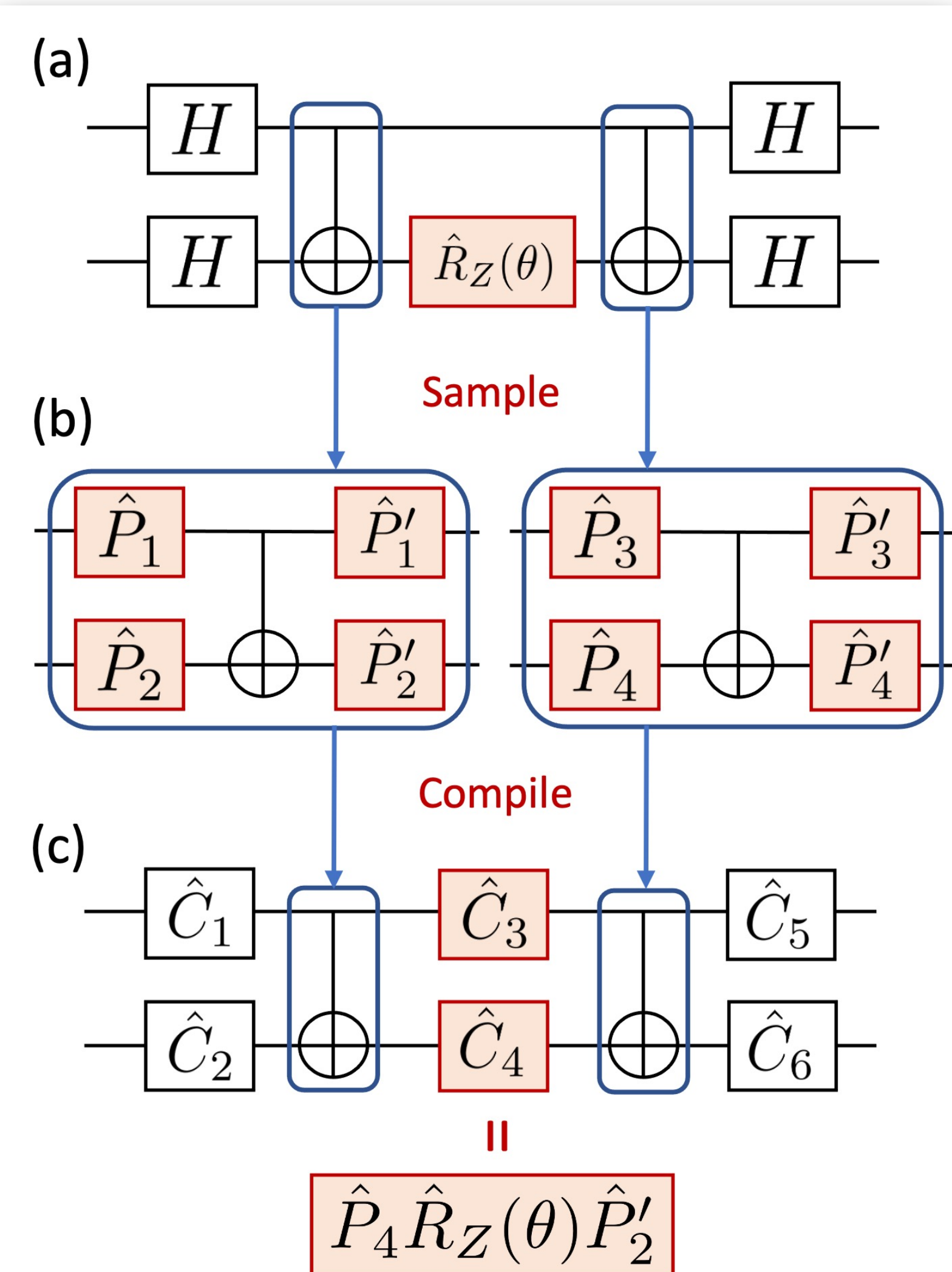
K-qubit stochastic Pauli channel: $\mathcal{E}(\rho) = \sum_k \epsilon_k \hat{P}_k \rho \hat{P}_k$

$$K=1: \mathcal{E}_m^{(1)}(\hat{\rho}) = \epsilon_0 \hat{\rho} + \epsilon_X \hat{X}_m \hat{\rho} \hat{X}_m + \epsilon_Y \hat{Y}_m \hat{\rho} \hat{Y}_m + \epsilon_Z \hat{Z}_m \hat{\rho} \hat{Z}_m$$

$$K=2: \mathcal{E}_{m,m+1}^{(2)}(\hat{\rho}) = \mathcal{E}_m^{(1)}(\hat{\rho}) + \mathcal{E}_{m+1}^{(1)}(\hat{\rho}) \\ + \epsilon_{XX} \hat{X}_m \hat{X}_{m+1} \hat{\rho} \hat{X}_m \hat{X}_{m+1} + \epsilon_{XY} \hat{X}_m \hat{Y}_{m+1} \hat{\rho} \hat{X}_m \hat{Y}_{m+1} + \dots$$

No need to characterize errors acting on more than K=2 nearest-neighbour qubits.

Randomized Compiling



$$\hat{G} = \hat{P}'_k \hat{G} \hat{P}_k, \quad \hat{P}'_k = \hat{G} \hat{P}_k \hat{G}^\dagger$$

Time-evolution via product formulas

- Time-evolution in the quantum computer,

$$\hat{H} = \sum_{j=1}^N \hat{H}_j, \quad \hat{H}_j = \alpha_j \hat{P}_j$$

Noiseless quantum computer: $e^{-i\hat{H}t} |\Psi(0)\rangle \approx \prod_{d=1}^D \hat{U}_k(\Delta t) |\Psi(0)\rangle, \quad \hat{U}_1(\Delta t) = \prod_{j=1}^N e^{-i\hat{H}_j \Delta t}, \quad \Delta t = t/D.$

Noisy quantum computer: $\frac{d\hat{\rho}(t)}{dt} = \mathcal{L}[\hat{\rho}(t)] = -i[\hat{H}, \hat{\rho}(t)] + \mathcal{D}_{\text{stochastic}}[\hat{\rho}(t)]$

- Markovian noise.
- Weak noise over a Trotter iteration.

Time-evolution via product formulas

- Time-evolution in the quantum computer,

$$\hat{H} = \sum_{j=1}^N \hat{H}_j, \quad \hat{H}_j = \alpha_j \hat{P}_j$$

Noiseless quantum computer: $e^{-i\hat{H}t} |\Psi(0)\rangle \approx \prod_{d=1}^D \hat{U}_k(\Delta t) |\Psi(0)\rangle, \quad \hat{U}_1(\Delta t) = \prod_{j=1}^N e^{-i\hat{H}_j \Delta t}, \quad \Delta t = t/D.$

Noisy quantum computer: $\frac{d\hat{\rho}(t)}{dt} = \mathcal{L}[\hat{\rho}(t)] = -i[\hat{H}, \hat{\rho}(t)] + \mathcal{D}_{\text{stochastic}}[\hat{\rho}(t)]$

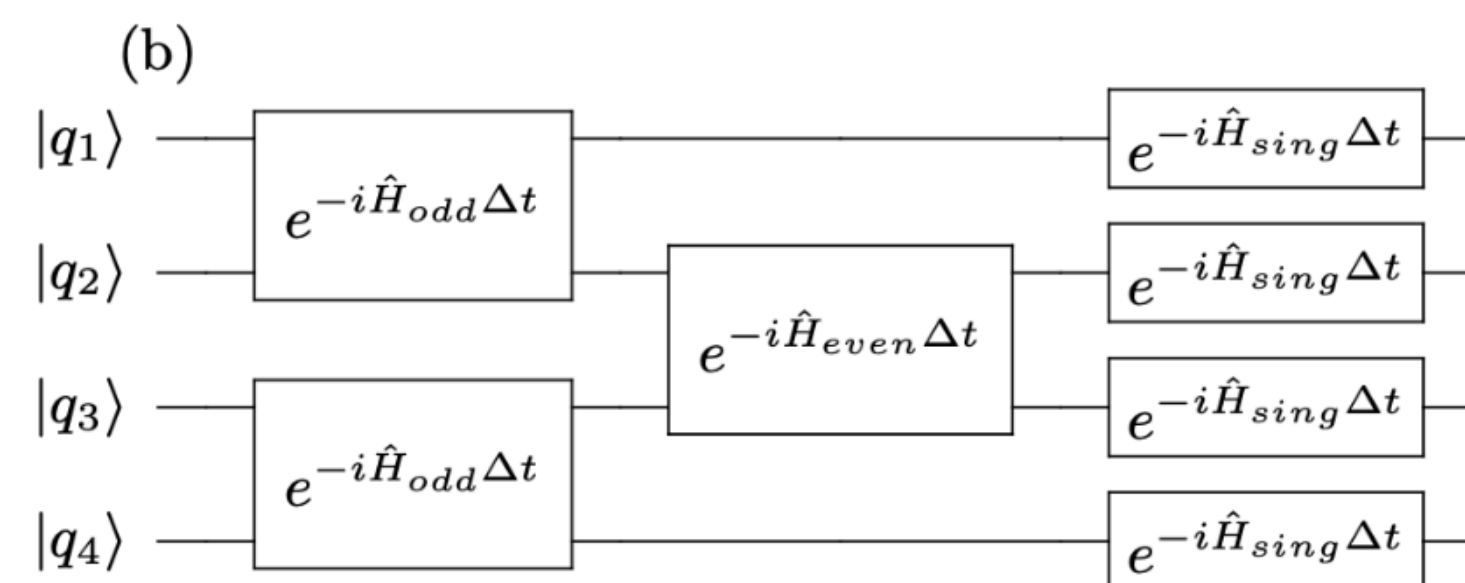
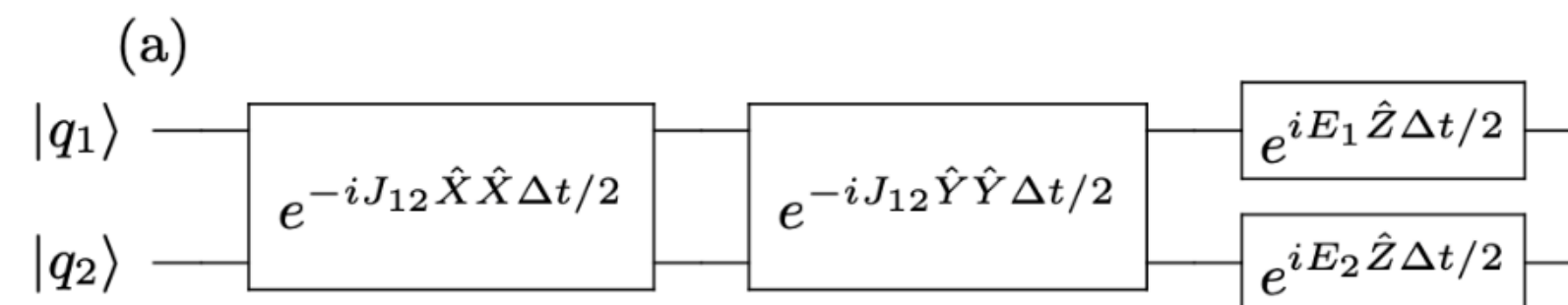
- Markovian noise.
- Weak noise over a Trotter iteration.

$$\mathcal{D}_{\text{stochastic}}[\hat{\rho}(t)] = \sum_{k=0}^{4^K-1} \gamma_k \left(\hat{P}_k \hat{\rho}(t) \hat{P}_k - \hat{\rho}(t) \right), \quad \gamma_k = \epsilon_k / \Delta t$$

K=2

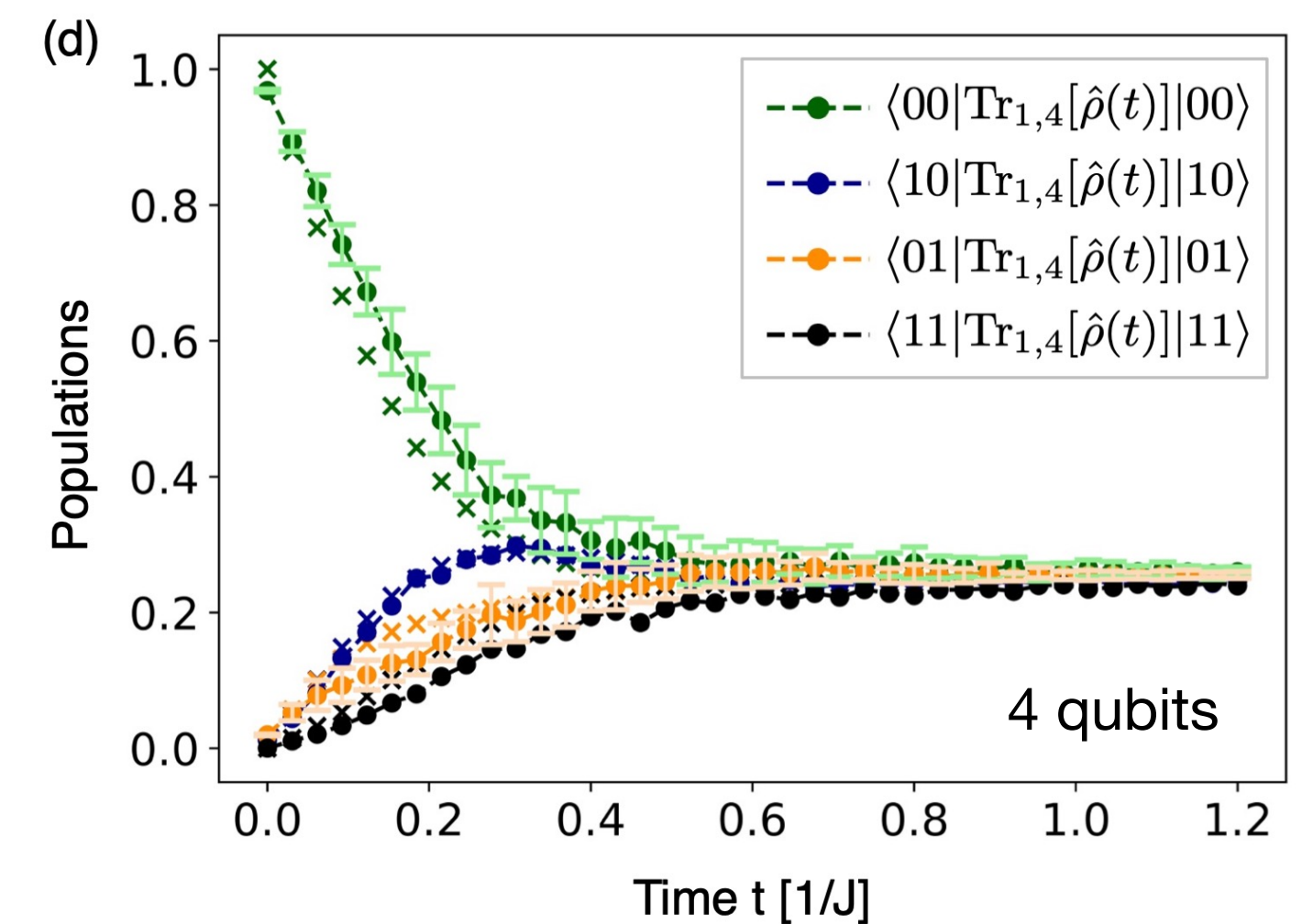
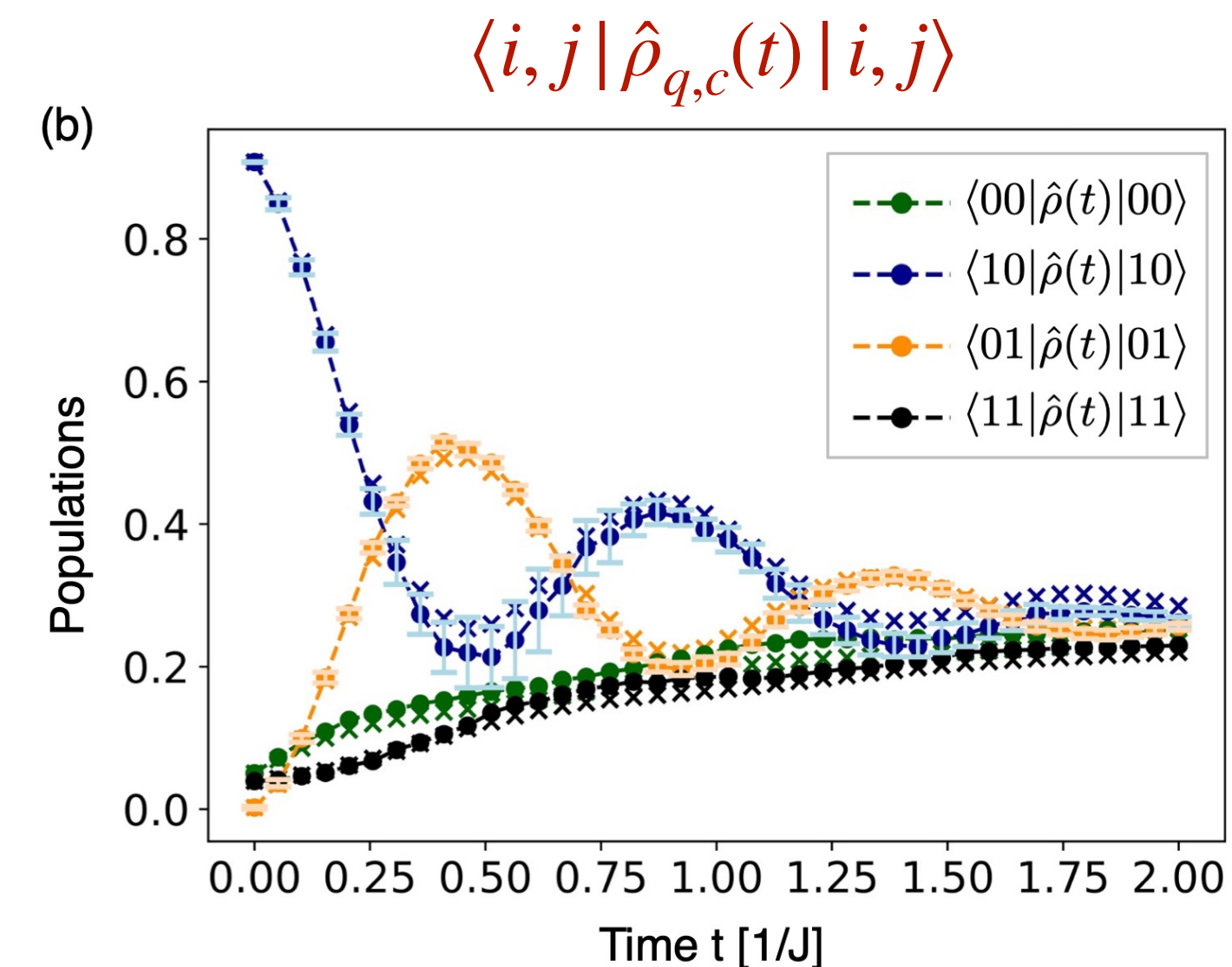
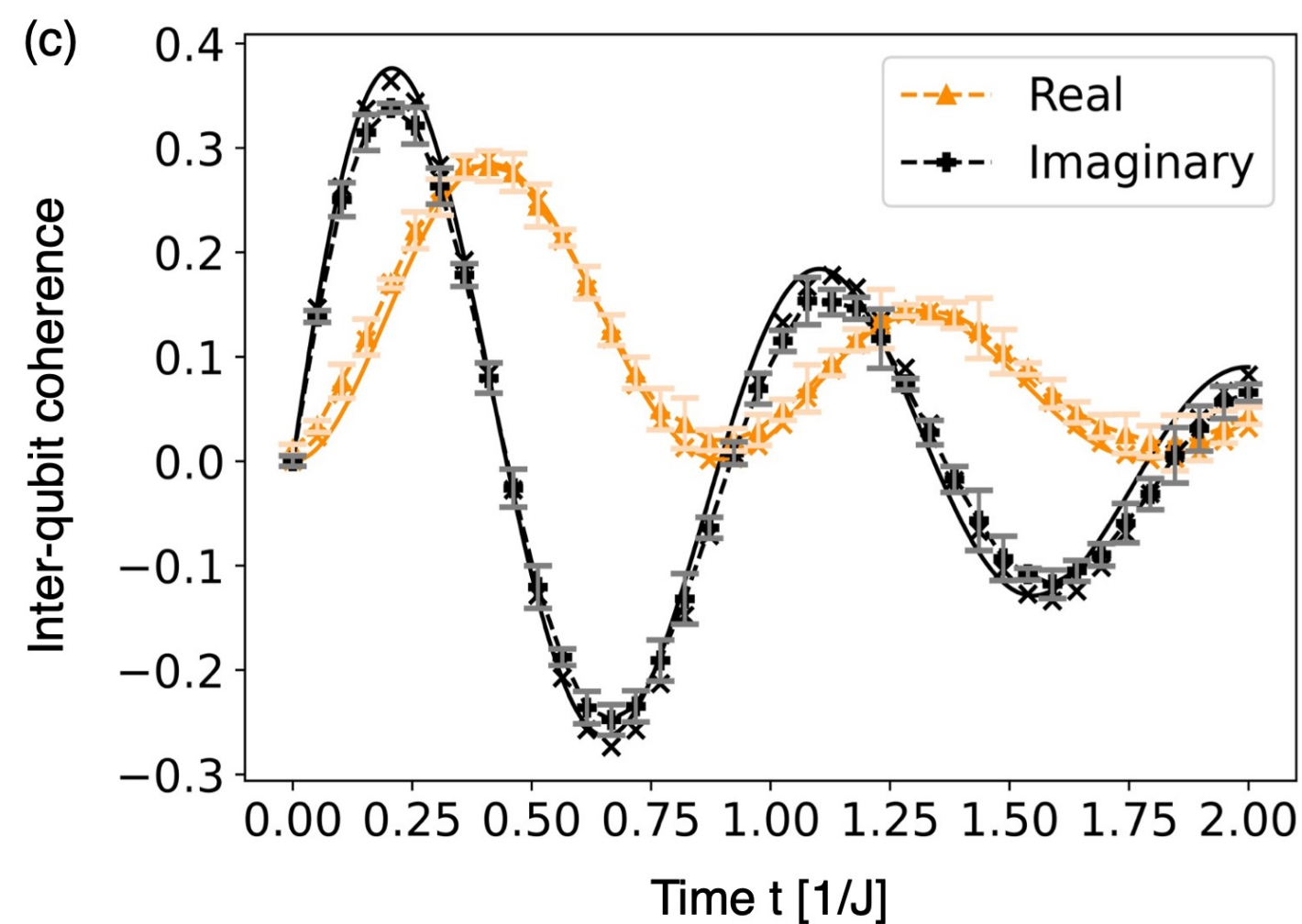
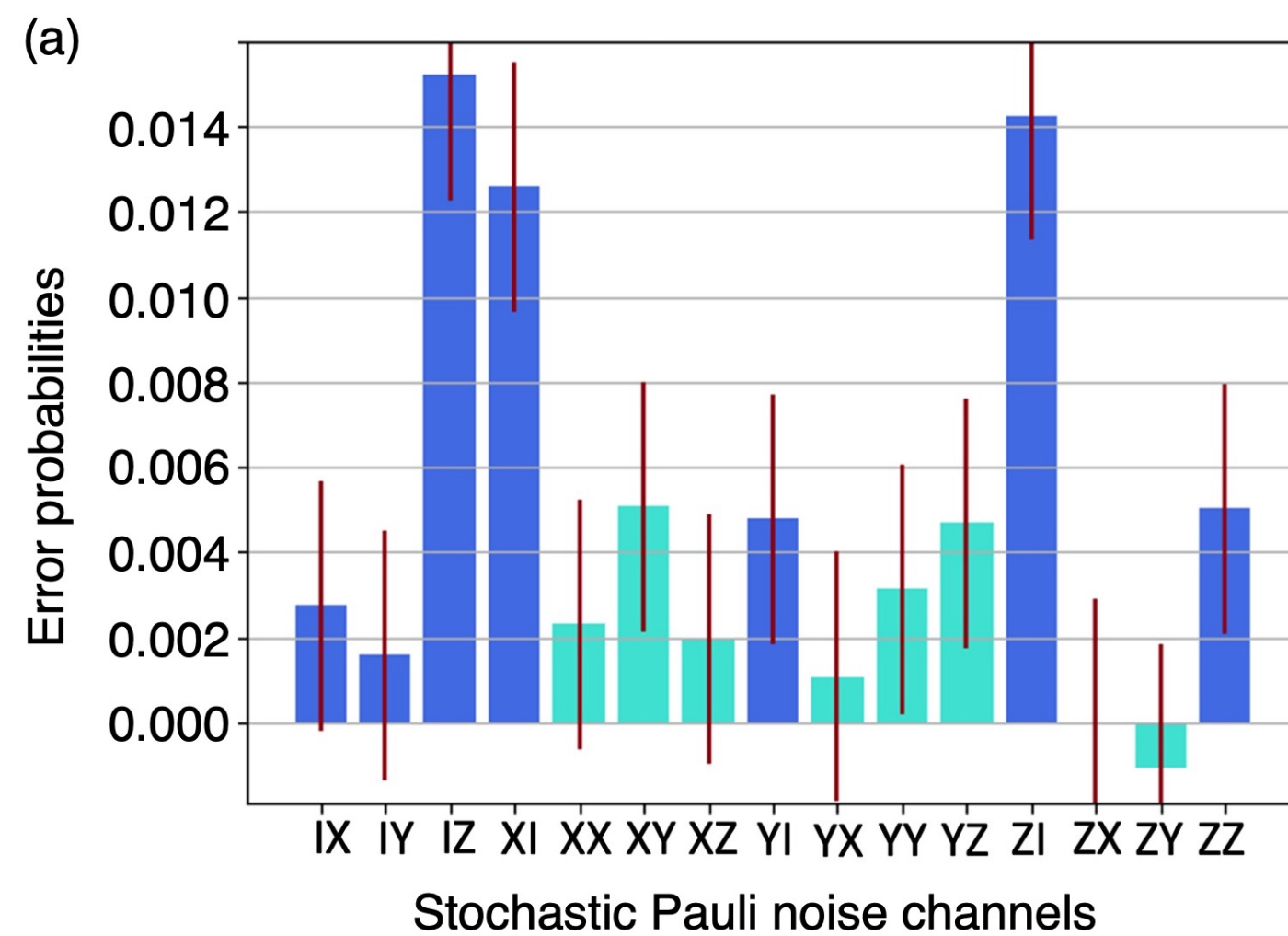
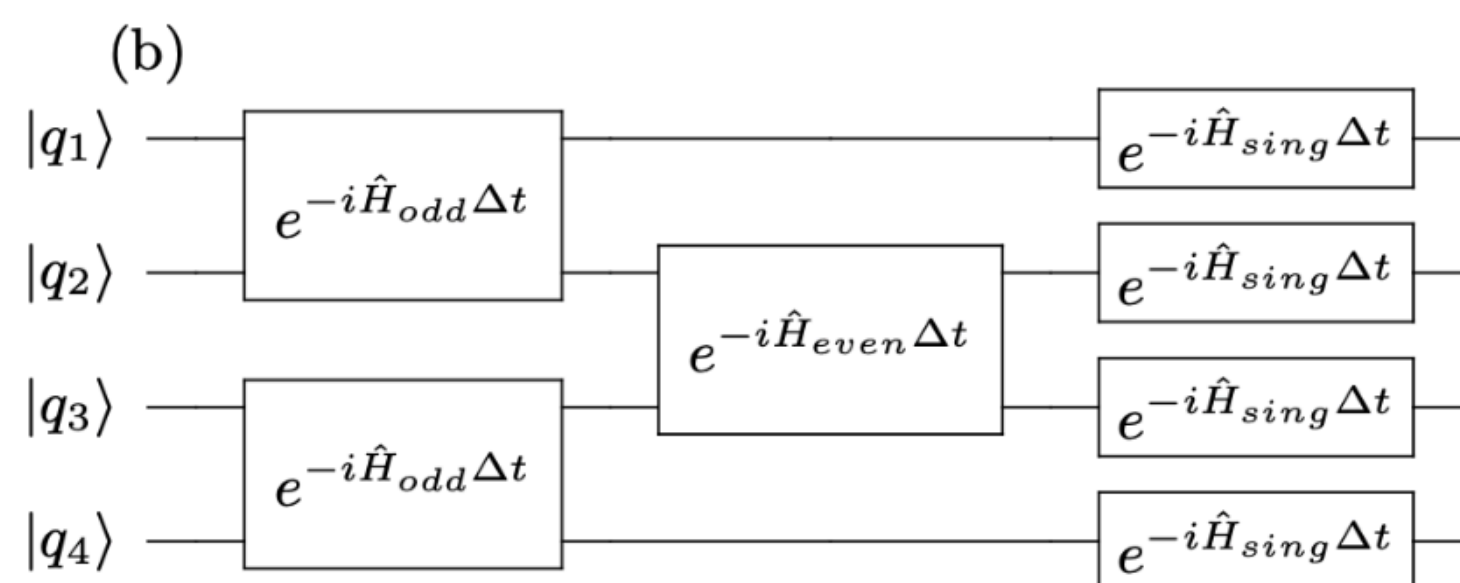
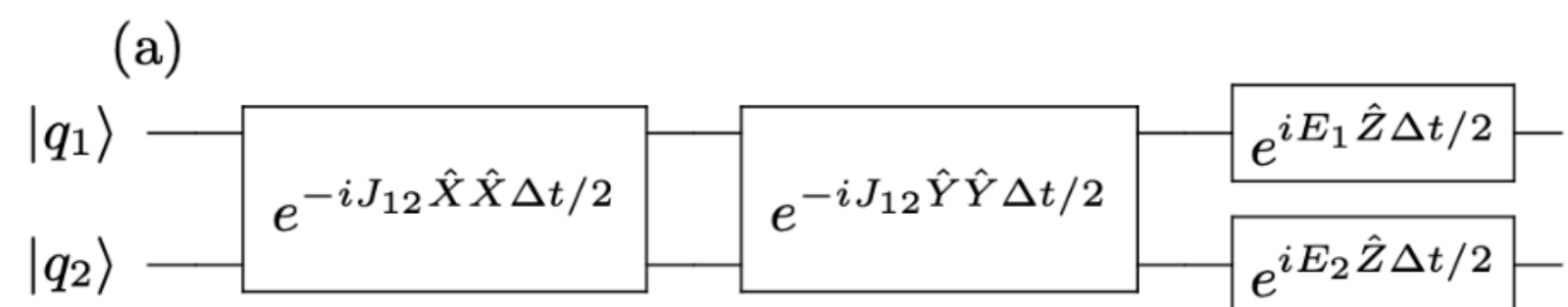
Time-evolution via product formulas

$$\hat{H} = - \sum_{m=1}^n \frac{E_m}{2} \hat{Z}_m + \sum_{m=1}^{n-1} \frac{J_{m,m+1}}{2} (\hat{X}_m \hat{X}_{m+1} + \hat{Y}_m \hat{Y}_{m+1})$$

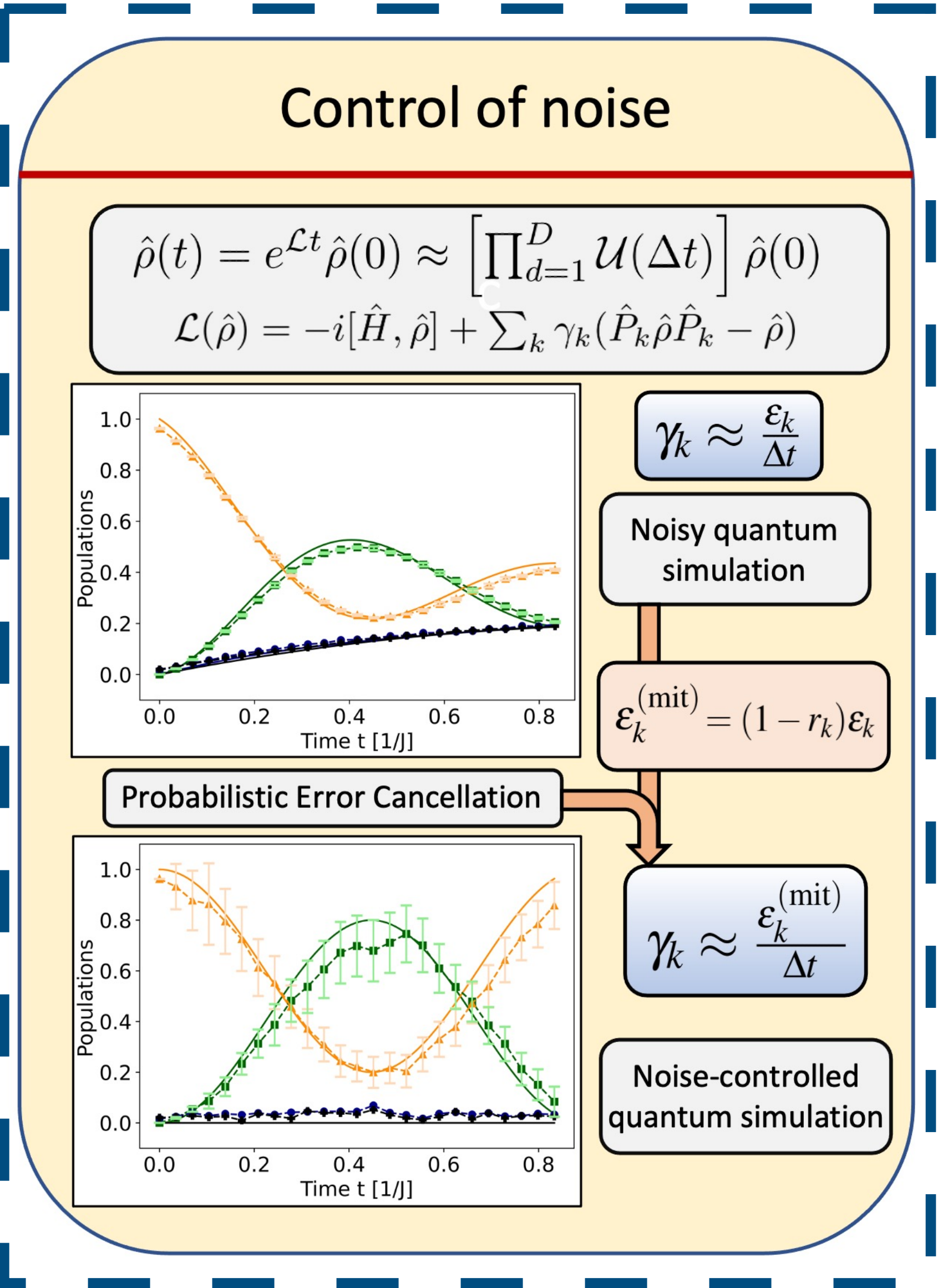
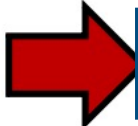
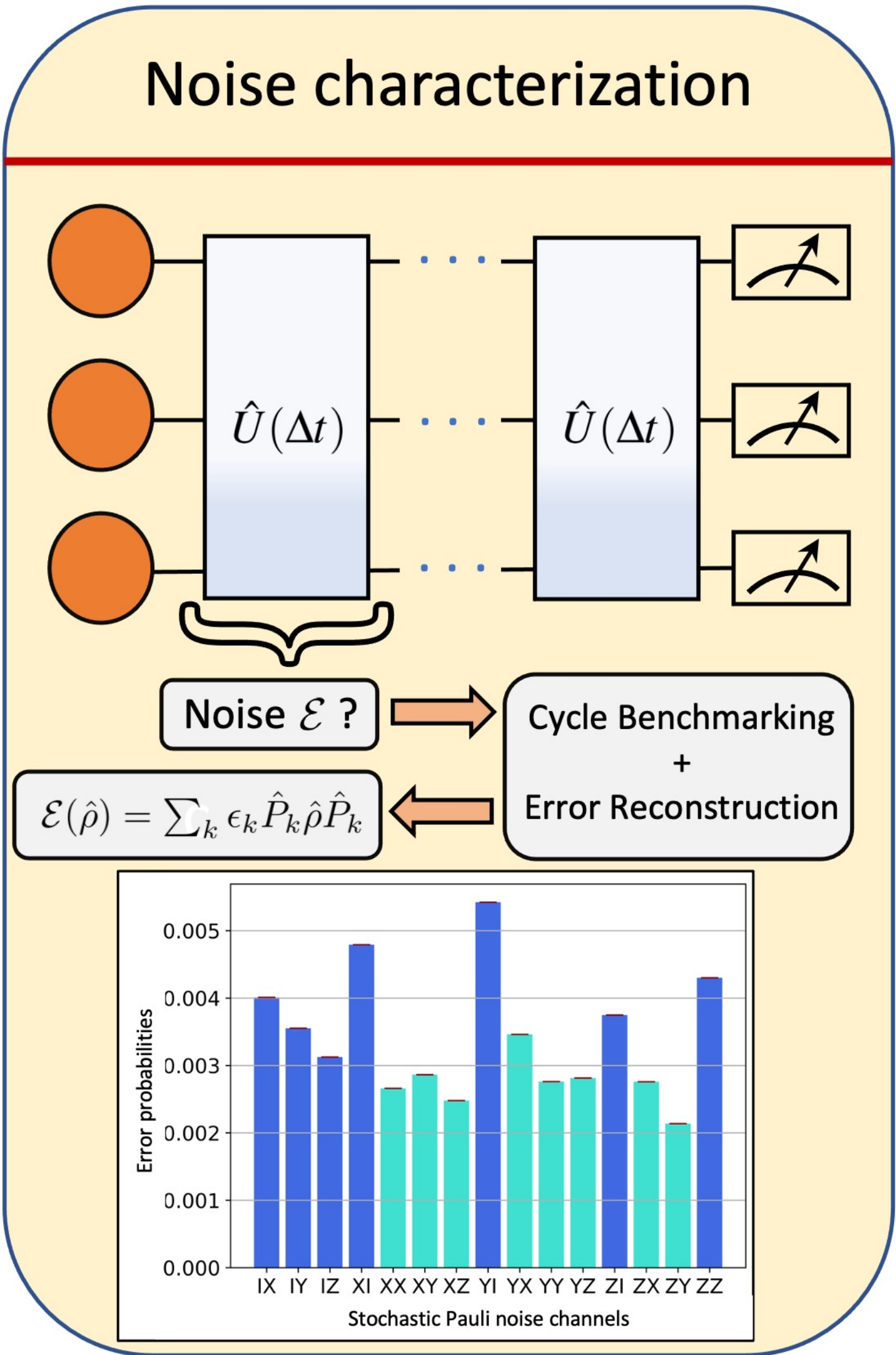


Time-evolution via product formulas

$$\hat{H} = - \sum_{m=1}^n \frac{E_m}{2} \hat{Z}_m + \sum_{m=1}^{n-1} \frac{J_{m,m+1}}{2} (\hat{X}_m \hat{X}_{m+1} + \hat{Y}_m \hat{Y}_{m+1})$$



Control of noise



Control of noise

$$\frac{d\hat{\rho}(t)}{dt} = \mathcal{L}[\hat{\rho}(t)] = -i[\hat{H}, \hat{\rho}(t)] + \mathcal{D}_{\text{stochastic}}[\hat{\rho}(t)]$$

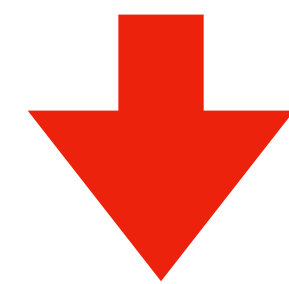
$$\mathcal{D}_{\text{stochastic}}[\hat{\rho}(t)] = \sum_{k=0}^{4^K-1} \gamma_k \left(\hat{P}_k \hat{\rho}(t) \hat{P}_k - \hat{\rho}(t) \right), \quad \gamma_k = \epsilon_k / \Delta t$$

How can we control γ_k in the digital simulation without changing the hardware components?

Control of noise

$$\frac{d\hat{\rho}(t)}{dt} = \mathcal{L}[\hat{\rho}(t)] = -i[\hat{H}, \hat{\rho}(t)] + \mathcal{D}_{\text{stochastic}}[\hat{\rho}(t)]$$

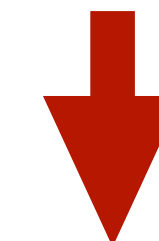
$$\mathcal{D}_{\text{stochastic}}[\hat{\rho}(t)] = \sum_{k=0}^{4^K-1} \gamma_k \left(\hat{P}_k \hat{\rho}(t) \hat{P}_k - \hat{\rho}(t) \right), \quad \gamma_k = \epsilon_k / \Delta t$$



Target decoherence rates Γ_k

$$\mathcal{D}_{\text{stochastic}}^{(\text{controlled})}[\hat{\rho}(t)] = \sum_{k=0}^{4^K-1} \Gamma_k \left(\hat{P}_k \hat{\rho}(t) \hat{P}_k - \hat{\rho}(t) \right), \quad \Gamma_k = \epsilon_k (1 - r_k) / \Delta t.$$

$$r_k \in [0, 1]$$



Probabilistic Error Cancellation

Endo, Suguru, Simon C. Benjamin, and Ying Li. *Physical Review X* 8.3 (2018): 031027.

Sun, Jinzhao, et al. *Physical Review Applied* 15.3 (2021): 034026.

Probabilistic Error Cancellation

Overview

- Probabilistically cancels Markovian noise to first order by inverting the noise channel.

Characterization of the noise channel acting in the circuit:

$$\mathcal{E}(\rho) = \epsilon_0 \rho + \sum_{k=1} \epsilon_k P_k \rho P_k$$

CPTP map

Inversion of the characterized stochastic Pauli channel:

$$\mathcal{E}^{-1}(\rho) = \epsilon'_0 \rho - \sum_{k=1} \epsilon'_k P_k \rho P_k$$

Non-CP map

$$\epsilon'_{k>0} = r_k \epsilon_k$$

Probabilistic Error Cancellation

Overview

- Probabilistically cancels Markovian noise to first order by inverting the noise channel.

Characterization of the noise channel acting in the circuit:

$$\mathcal{E}(\rho) = \epsilon_0 \rho + \sum_{k=1} \epsilon_k P_k \rho P_k$$

CPTP map

Inversion of the characterized stochastic Pauli channel:

$$\mathcal{E}^{-1}(\rho) = \epsilon'_0 \rho - \sum_{k=1} \epsilon'_k P_k \rho P_k$$

Non-CP map

For each Trotter iteration apply



$$\mathcal{E}^{-1}(\rho) = \sum_{k=0} q_k \mathcal{P}_k(\rho) = \sum_{k=0} q_k P_k \rho P_k, \quad q_k = \pm \epsilon'_k$$

$$\epsilon'_{k>0} = r_k \epsilon_k$$

Probabilistic Error Cancellation

Overview

- Probabilistically cancels Markovian noise to first order by inverting the noise channel.

Characterization of the noise channel acting in the circuit:

$$\mathcal{E}(\rho) = \epsilon_0 \rho + \sum_{k=1} \epsilon_k P_k \rho P_k$$

CPTP map

Inversion of the characterized stochastic Pauli channel:

$$\mathcal{E}^{-1}(\rho) = \epsilon'_0 \rho - \sum_{k=1} \epsilon'_k P_k \rho P_k$$

Non-CP map

For each Trotter iteration apply

Probabilistic application of Pauli gates

$$\mathcal{E}^{-1}(\rho) = \sum_{k=0} q_k \mathcal{P}_k(\rho) = \sum_{k=0} q_k P_k \rho P_k, \quad q_k = \pm \epsilon'_k$$

$$\mathcal{E}^{-1} = C \sum_{k=0} p_k \text{sign}(q_k) \mathcal{P}_k$$

$$\epsilon'_{k>0} = r_k \epsilon_k$$

$$p_k = \epsilon'_k / C$$

$$C = \sum_{k=0} |q_k|$$

Probabilistic Error Cancellation

Overview

- Probabilistically cancels Markovian noise to first order by inverting the noise channel.

Characterization of the noise channel acting in the circuit:

$$\mathcal{E}(\rho) = \epsilon_0 \rho + \sum_{k=1} \epsilon_k P_k \rho P_k$$

CPTP map

Inversion of the characterized stochastic Pauli channel:

$$\mathcal{E}^{-1}(\rho) = \epsilon'_0 \rho - \sum_{k=1} \epsilon'_k P_k \rho P_k$$

Non-CP map

For each Trotter iteration apply

Probabilistic application of Pauli gates

$$\mathcal{E}^{-1}(\rho) = \sum_{k=0} q_k \mathcal{P}_k(\rho) = \sum_{k=0} q_k P_k \rho P_k, \quad q_k = \pm \epsilon'_k$$

$$\mathcal{E}^{-1} = C \sum_{k=0} p_k \text{sign}(q_k) \mathcal{P}_k$$

$$\epsilon'_{k>0} = r_k \epsilon_k$$

$$p_k = \epsilon'_k / C$$

$$C = \sum_{k=0} |q_k|$$

Probability of sampling P_k

Probabilistic Error Cancellation

Overview

- Probabilistically cancels Markovian noise to first order by inverting the noise channel.

Characterization of the noise channel acting in the circuit:

$$\mathcal{E}(\rho) = \epsilon_0 \rho + \sum_{k=1} \epsilon_k P_k \rho P_k$$

CPTP map

Inversion of the characterized stochastic Pauli channel:

$$\mathcal{E}^{-1}(\rho) = \epsilon'_0 \rho - \sum_{k=1} \epsilon'_k P_k \rho P_k$$

Non-CP map

For each Trotter iteration apply

Probabilistic application of Pauli gates

$$\mathcal{E}^{-1}(\rho) = \sum_{k=0} q_k \mathcal{P}_k(\rho) = \sum_{k=0} q_k P_k \rho P_k, \quad q_k = \pm \epsilon'_k$$

$$\mathcal{E}^{-1} = C \sum_{k=0} p_k \text{sign}(q_k) \mathcal{P}_k \quad \epsilon'_{k>0} = r_k \epsilon_k$$

$$p_k = \epsilon'_k / C$$

$$C = \sum_{k=0} |q_k|$$

Mitigation cost

Probabilistic Error Cancellation

Overview

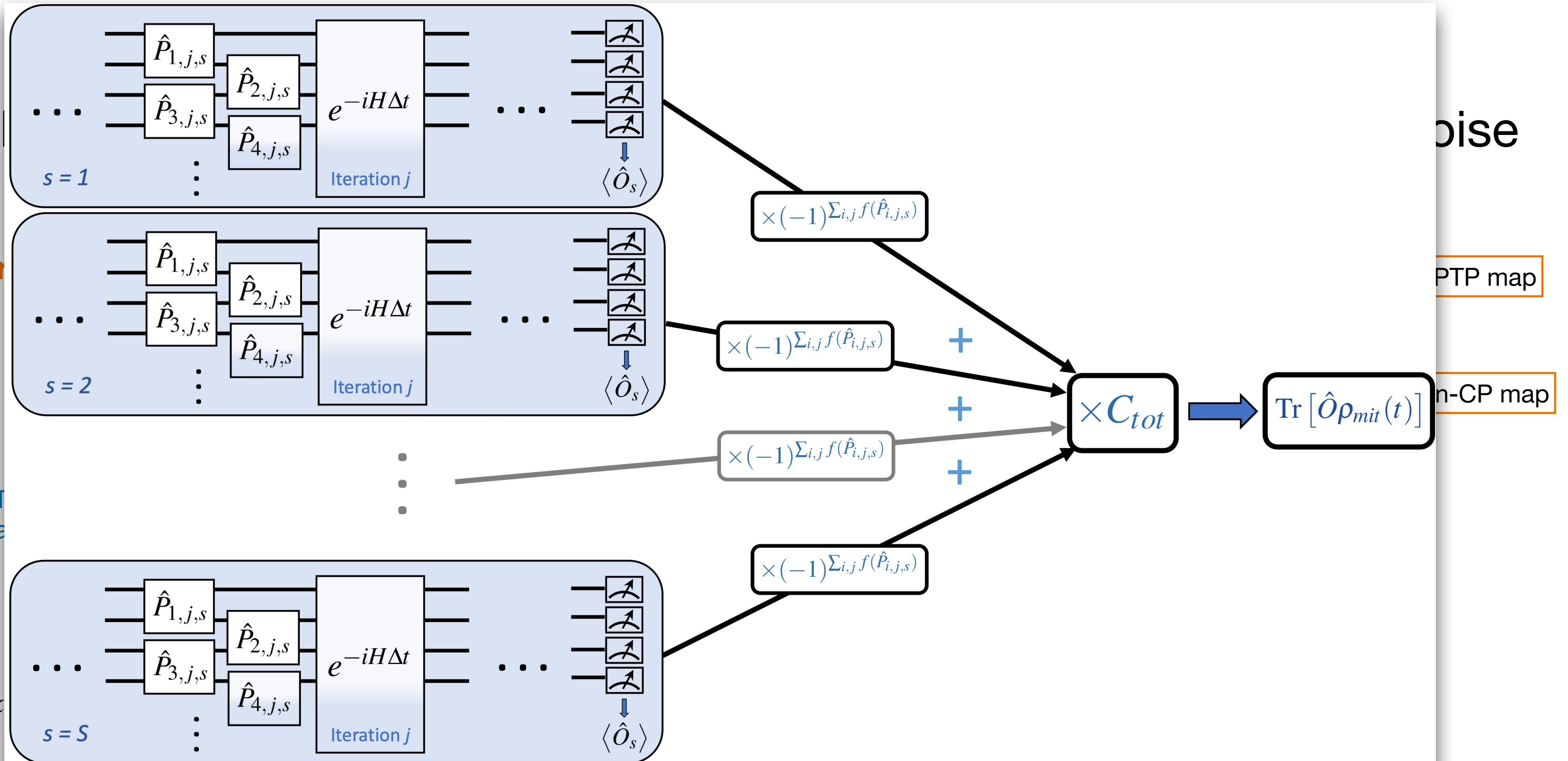
- Probabilistic channel

Character

Inversion

For each T iteration a

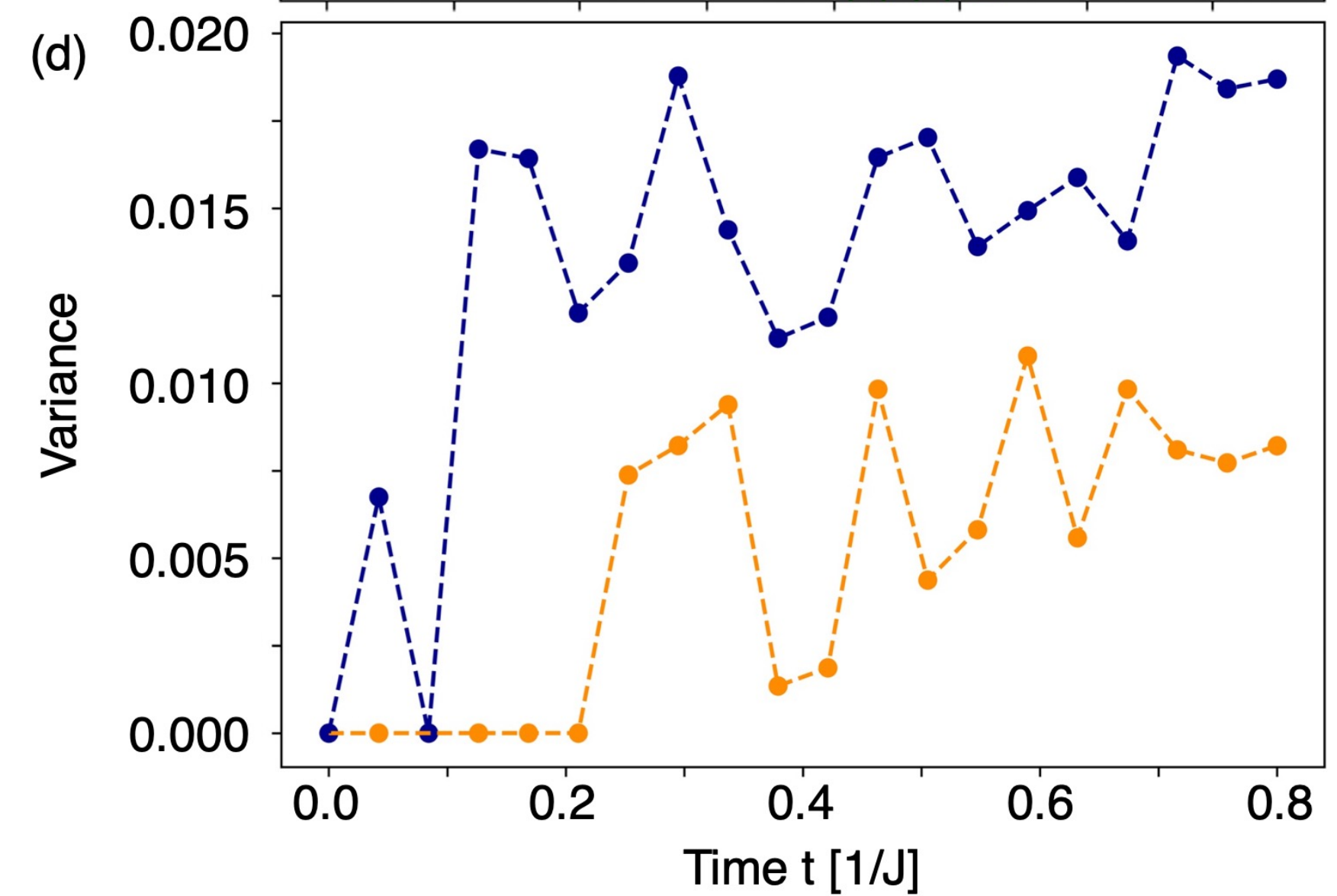
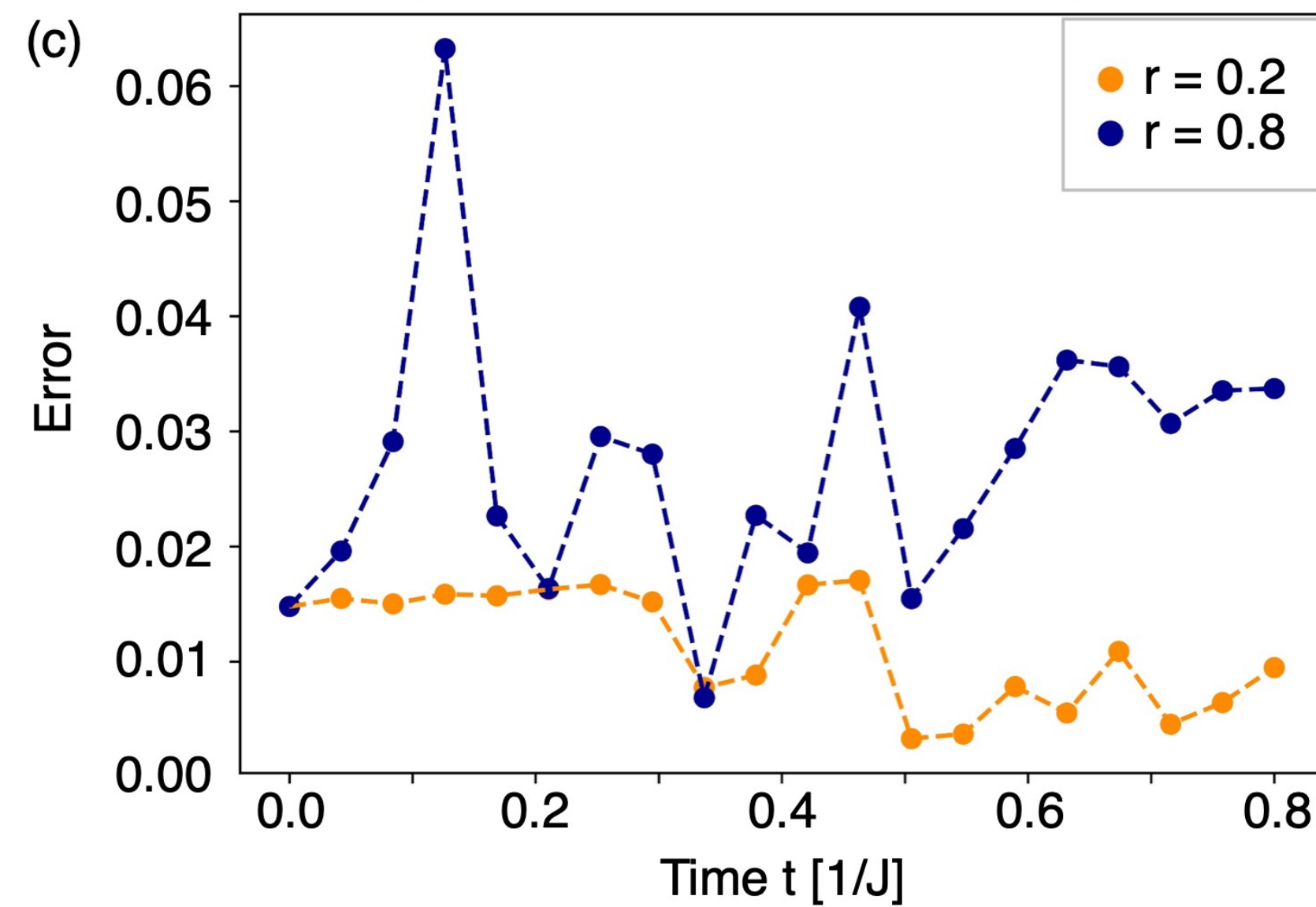
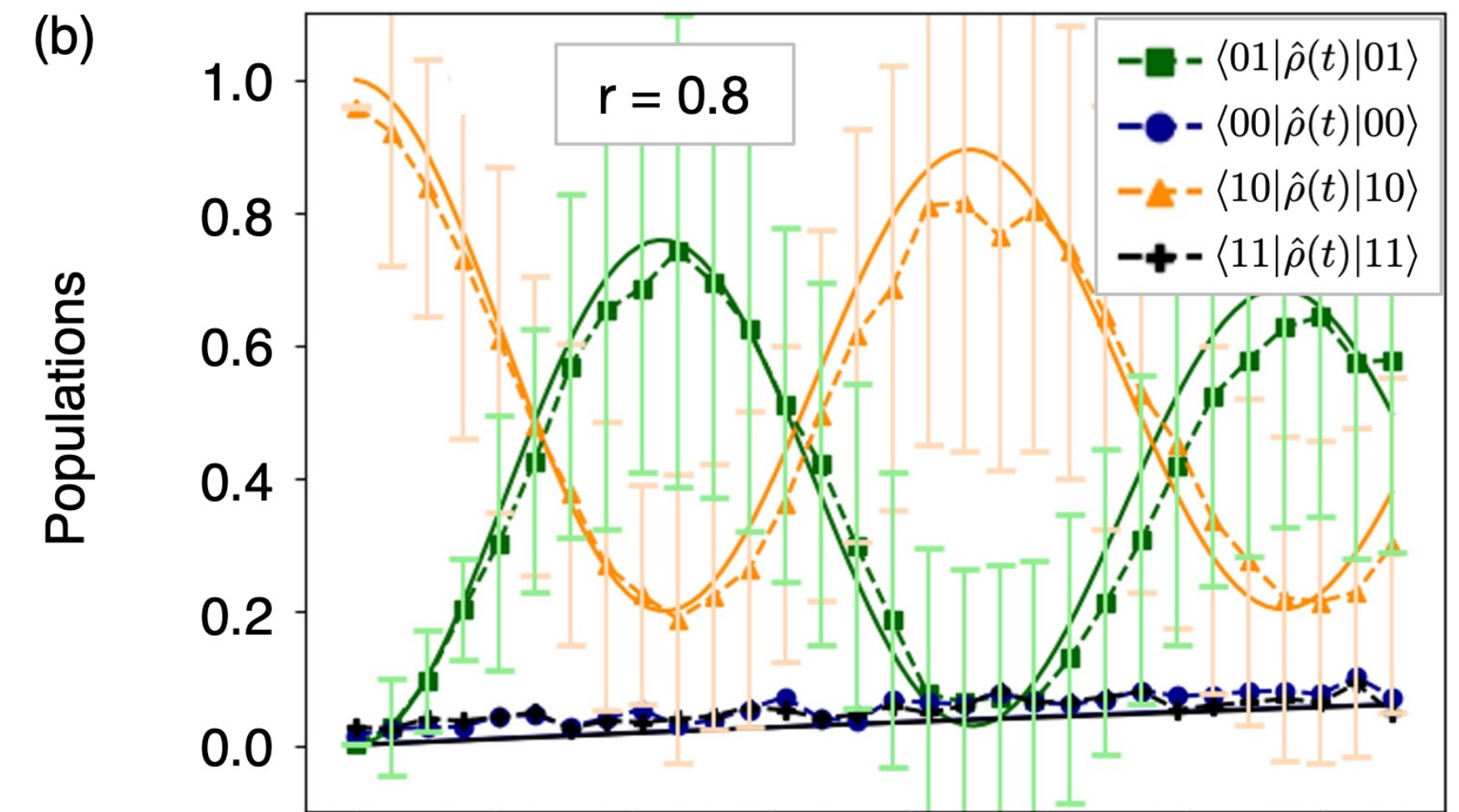
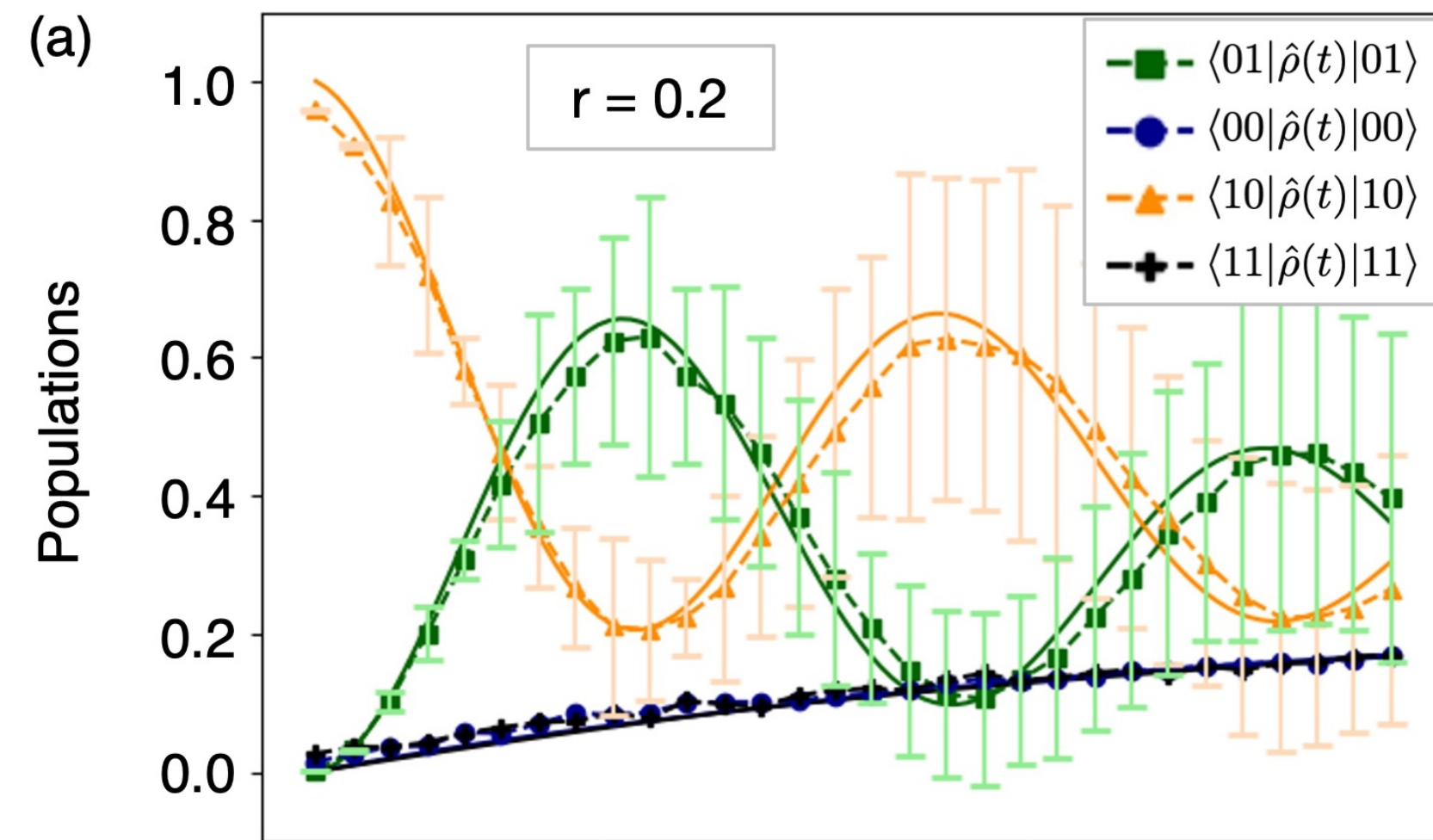
$$\mathcal{E}^{-1}(\rho) = \sum_{k=0} q_k$$



Implementation

$$\epsilon'_{k>0} = r\epsilon_k$$

$$C = \sum_{k=0} |q_k| = 1 + 2r \sum_{k=1} \epsilon_k$$

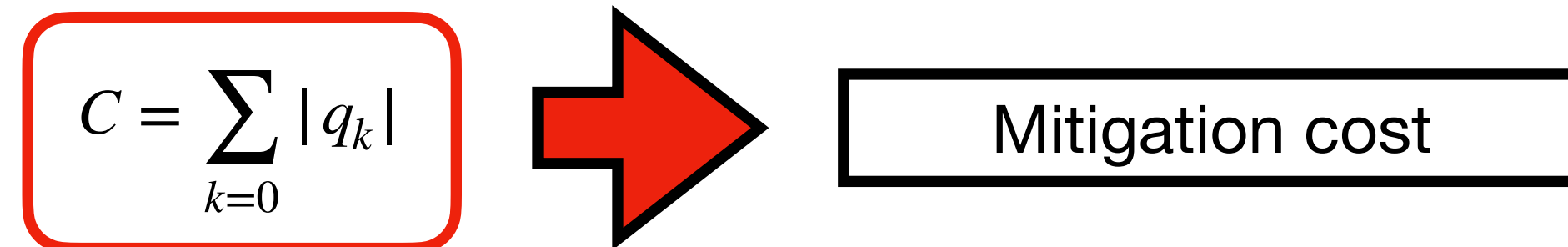


Partial Probabilistic Error Cancellation

Mitigation Cost

$$\mathcal{E}^{-1} = C \sum_{k=0} p_k \text{sign}(q_k) \mathcal{P}_k$$

$$p_k = \epsilon'_k / C$$



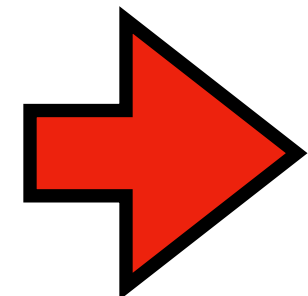
Partial Probabilistic Error Cancellation

Mitigation Cost

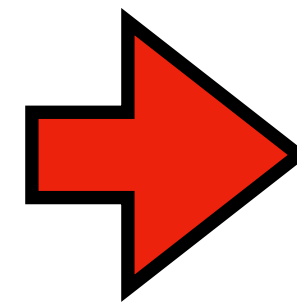
$$\mathcal{E}^{-1} = C \sum_{k=0} p_k \text{sign}(q_k) \mathcal{P}_k$$

$$p_k = \epsilon'_k / C$$

$$C = \sum_{k=0} |q_k|$$



Mitigation cost



Variance of the measured observable is increased

$$\Delta O_M \propto M^{-1} \quad \rightarrow \quad \Delta O_M^{(\text{PEC})} \propto C_{\text{tot}}^2 M^{-1}$$

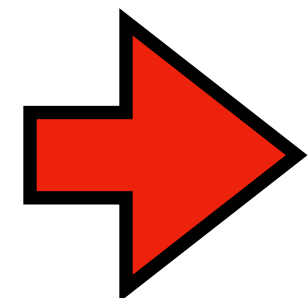
Partial Probabilistic Error Cancellation

Mitigation Cost

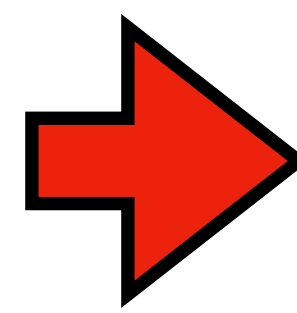
$$\mathcal{E}^{-1} = C \sum_{k=0} p_k \text{sign}(q_k) \mathcal{P}_k$$

$$p_k = \epsilon'_k / C$$

$$C = \sum_{k=0} |q_k|$$



Mitigation cost



Variance of the measured observable is increased

$$\Delta O_M \propto M^{-1} \quad \Rightarrow \quad \Delta O_M^{(\text{PEC})} \propto C_{\text{tot}}^2 M^{-1}$$

For a Trotter-type circuit:

$$C_{\text{tot}}^2 \sim e^{\lambda n D \epsilon_r}$$

$$\epsilon_r = \sum_{k=1} \epsilon'_k = \sum_{k=1} r_k \epsilon_k$$

Decoherence rate control scheme

How can we control γ_k in the digital simulation without changing the hardware components?

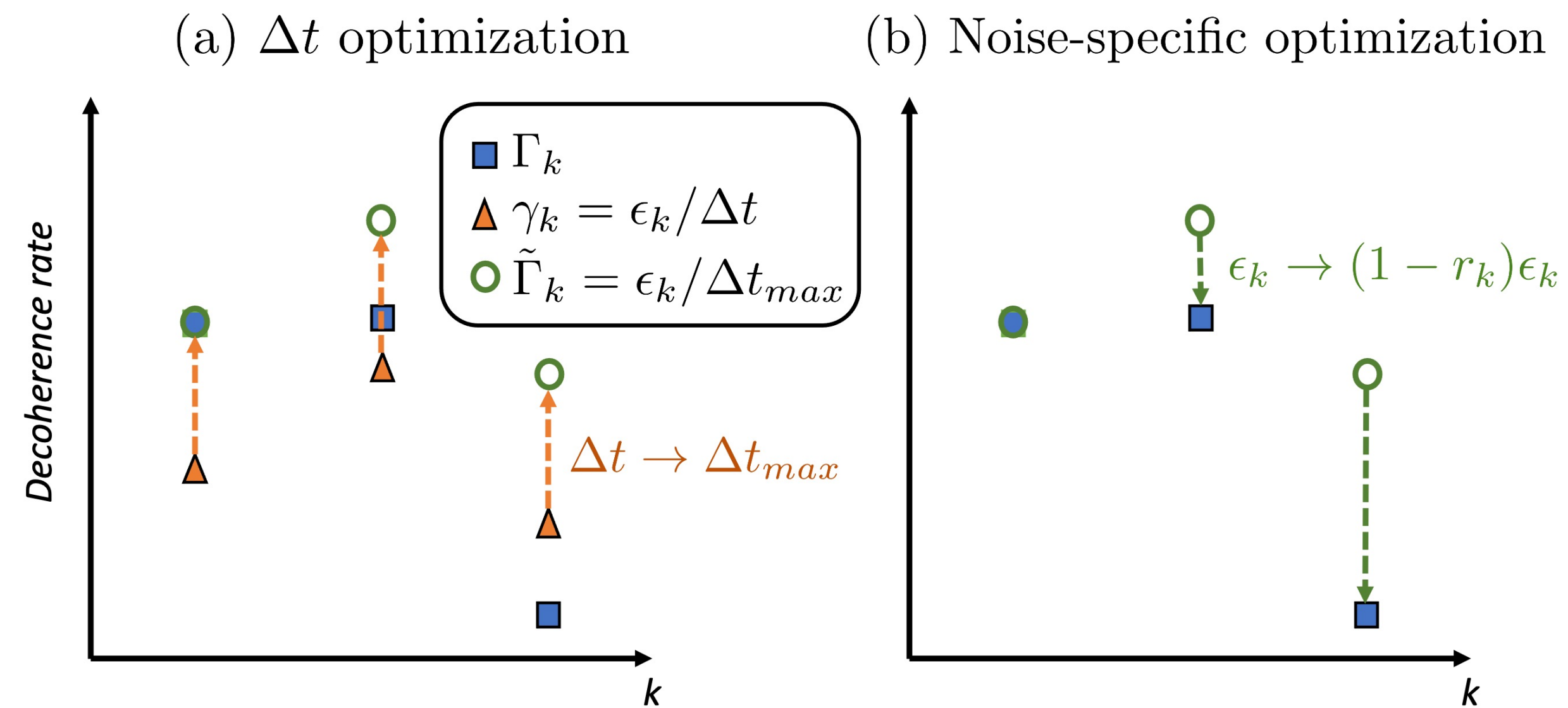
Target decoherence rates Γ_k :

$$\mathcal{D}_{\text{stochastic}}^{(\text{controlled})}[\hat{\rho}(t)] = \sum_{k=0}^{4^K-1} \Gamma_k \left(\hat{P}_k \hat{\rho}(t) \hat{P}_k - \hat{\rho}(t) \right)$$

Decoherence rate control scheme

How can we control γ_k in the digital simulation without changing the hardware components?

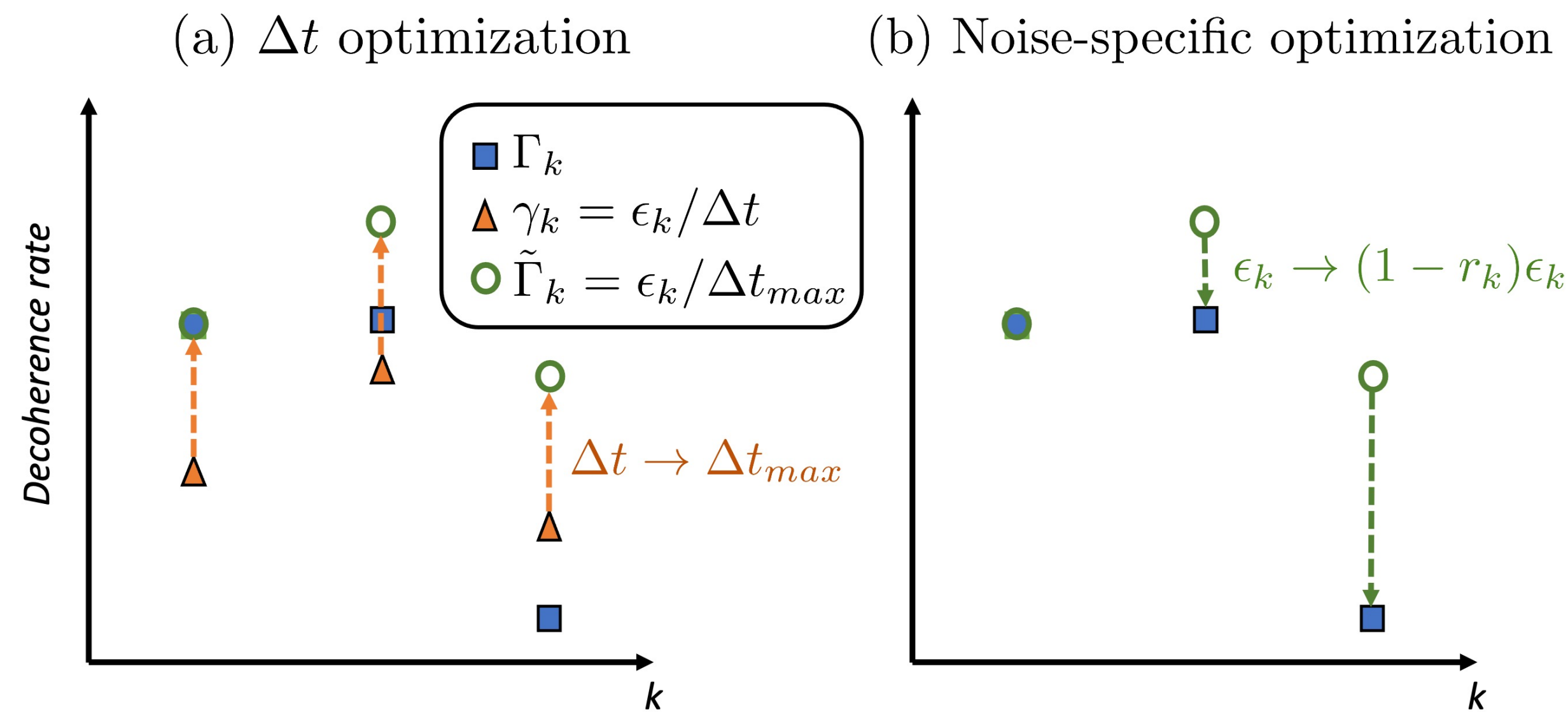
Target decoherence rates Γ_k :
$$\mathcal{D}_{\text{stochastic}}^{(\text{controlled})}[\hat{\rho}(t)] = \sum_{k=0}^{4^K-1} \Gamma_k \left(\hat{P}_k \hat{\rho}(t) \hat{P}_k - \hat{\rho}(t) \right)$$



Decoherence rate control scheme

How can we control γ_k in the digital simulation without changing the hardware components?

Target decoherence rates Γ_k :
$$\mathcal{D}_{\text{stochastic}}^{(\text{controlled})}[\hat{\rho}(t)] = \sum_{k=0}^{4^K-1} \Gamma_k \left(\hat{P}_k \hat{\rho}(t) \hat{P}_k - \hat{\rho}(t) \right)$$



$$\Gamma_k = \epsilon_k(1 - r_k) / \Delta t_{max}$$

Limitations of the technique

Target decoherence rates Γ_k :

$$\Gamma_k = \epsilon_k(1 - r_k)/\Delta t$$

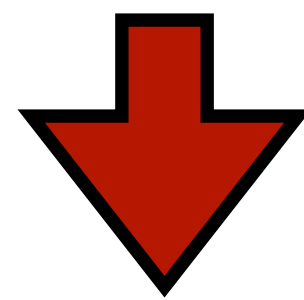
$$C_{\text{tot}}^2 \sim e^{\lambda n D \epsilon_r} \lesssim M_{\text{max}}^{(\text{NISQ})}$$

Limitations of the technique

Target decoherence rates Γ_k :

$$\Gamma_k = \epsilon_k(1 - r_k)/\Delta t$$

$$C_{\text{tot}}^2 \sim e^{\lambda n D \epsilon_r} \lesssim M_{\text{max}}^{(\text{NISQ})}$$



$$\epsilon \lesssim \frac{\Gamma t}{D} + \frac{\ln(M_{\text{max}}^{(\text{NISQ})})}{2\lambda n D^2}$$

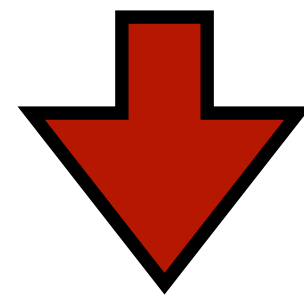
$$\epsilon = \sum_{k=1} \epsilon_k \quad \Gamma = \sum_{k=1} \Gamma_k$$

Limitations of the technique

Target decoherence rates Γ_k :

$$\Gamma_k = \epsilon_k(1 - r_k)/\Delta t$$

$$C_{\text{tot}}^2 \sim e^{\lambda n D \epsilon_r} \lesssim M_{\text{max}}^{(\text{NISQ})}$$



How does D scale?

$$\epsilon \lesssim \frac{\Gamma t}{D} + \frac{\ln(M_{\text{max}}^{(\text{NISQ})})}{2\lambda n D^2}$$

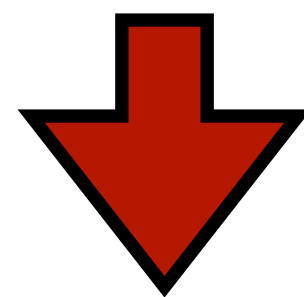
$$\epsilon = \sum_{k=1} \epsilon_k \quad \Gamma = \sum_{k=1} \Gamma_k$$

Limitations of the technique

Target decoherence rates Γ_k :

$$\Gamma_k = \epsilon_k(1 - r_k)/\Delta t$$

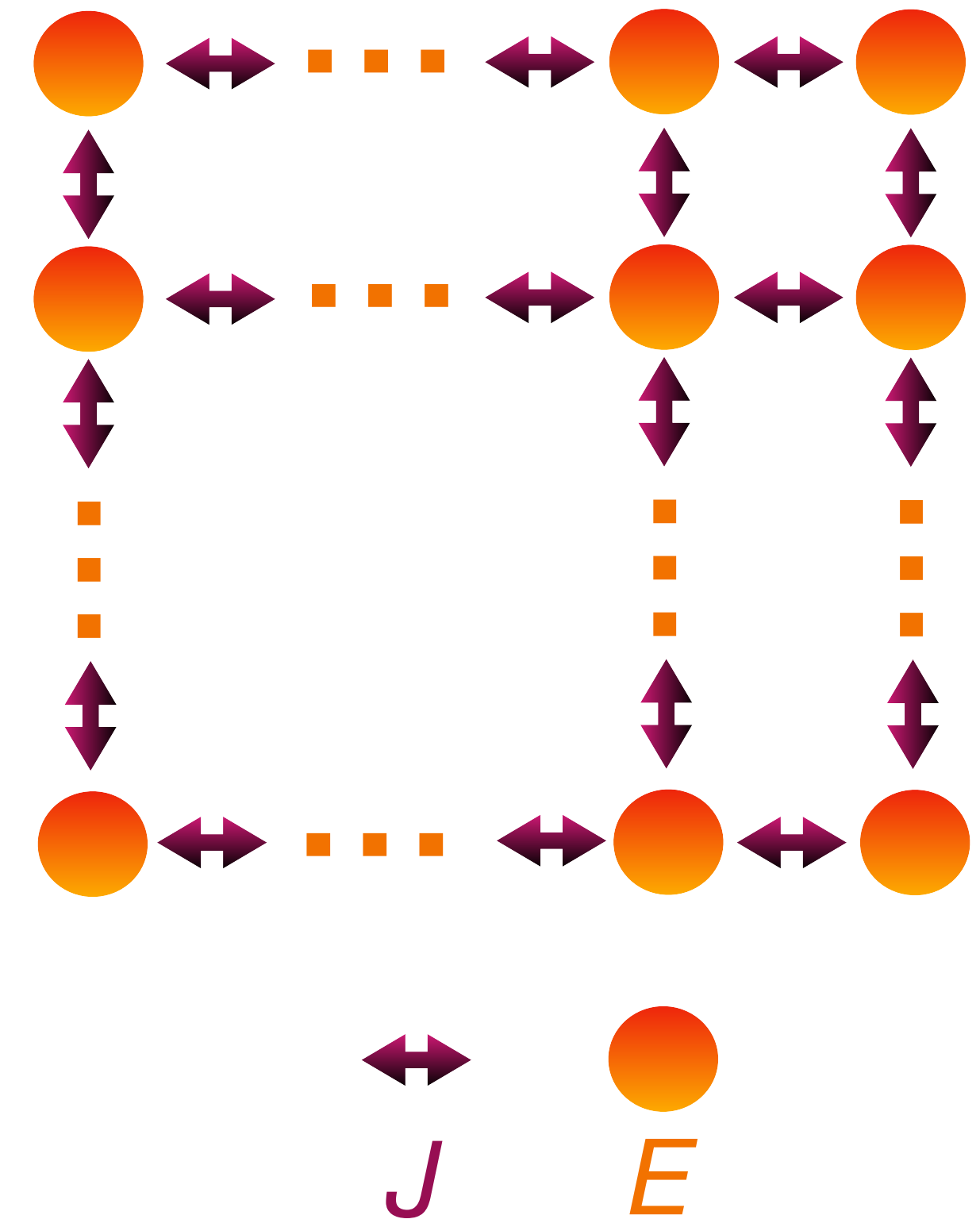
$$C_{\text{tot}}^2 \sim e^{\lambda n D \epsilon_r} \lesssim M_{\text{max}}^{(\text{NISQ})}$$



How does D scale?

$$\epsilon \lesssim \frac{\Gamma t}{D} + \frac{\ln(M_{\text{max}}^{(\text{NISQ})})}{2\lambda n D^2}$$

$$\epsilon = \sum_{k=1} \epsilon_k \quad \Gamma = \sum_{k=1} \Gamma_k$$



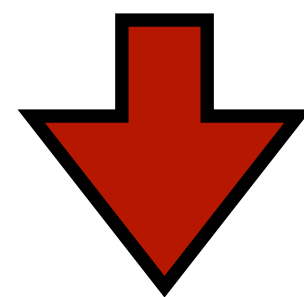
$$\hat{H} = - \sum_{m=1}^n \frac{E}{2} \hat{Z}_m + \sum_{\langle m, m' \rangle} \frac{J}{2} (\hat{X}_m \hat{X}_{m'} + \hat{Y}_m \hat{Y}_{m'})$$

Limitations of the technique

Target decoherence rates Γ_k :

$$\Gamma_k = \epsilon_k(1 - r_k)/\Delta t$$

$$C_{\text{tot}}^2 \sim e^{\lambda n D \epsilon_r} \lesssim M_{\text{max}}^{(\text{NISQ})}$$

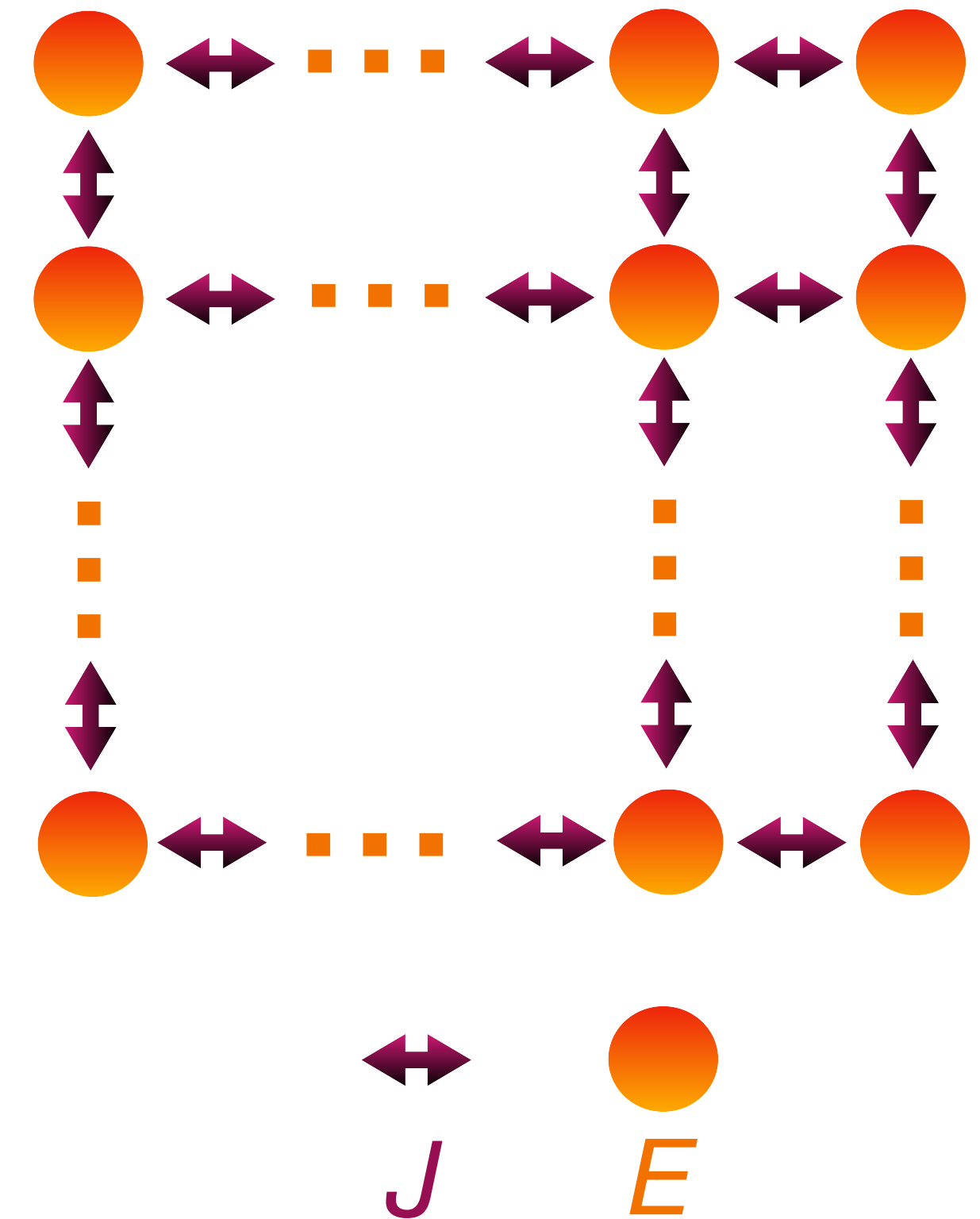


$$\epsilon \lesssim \frac{\Gamma t}{D} + \frac{\ln(M_{\text{max}}^{(\text{NISQ})})}{2\lambda n D^2}$$

$$\epsilon = \sum_{k=1} \epsilon_k \quad \Gamma = \sum_{k=1} \Gamma_k$$

Childs, Andrew M., et al. Physical Review X 11.1 (2021): 011020.

$$D = O\left(\frac{n^d J(J+E)t^2}{\epsilon_{\text{Trot}}}\right)$$



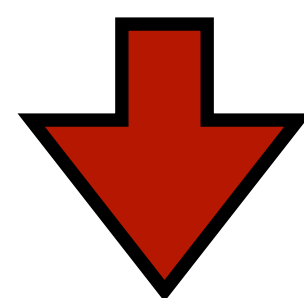
$$\hat{H} = -\sum_{m=1}^n \frac{E}{2} \hat{Z}_m + \sum_{\langle m, m' \rangle} \frac{J}{2} (\hat{X}_m \hat{X}_{m'} + \hat{Y}_m \hat{Y}_{m'})$$

Limitations of the technique

Target decoherence rates Γ_k :

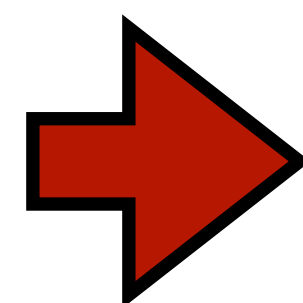
$$\Gamma_k = \epsilon_k(1 - r_k)/\Delta t$$

$$C_{\text{tot}}^2 \sim e^{\lambda n D \epsilon_r} \lesssim M_{\text{max}}^{(\text{NISQ})}$$

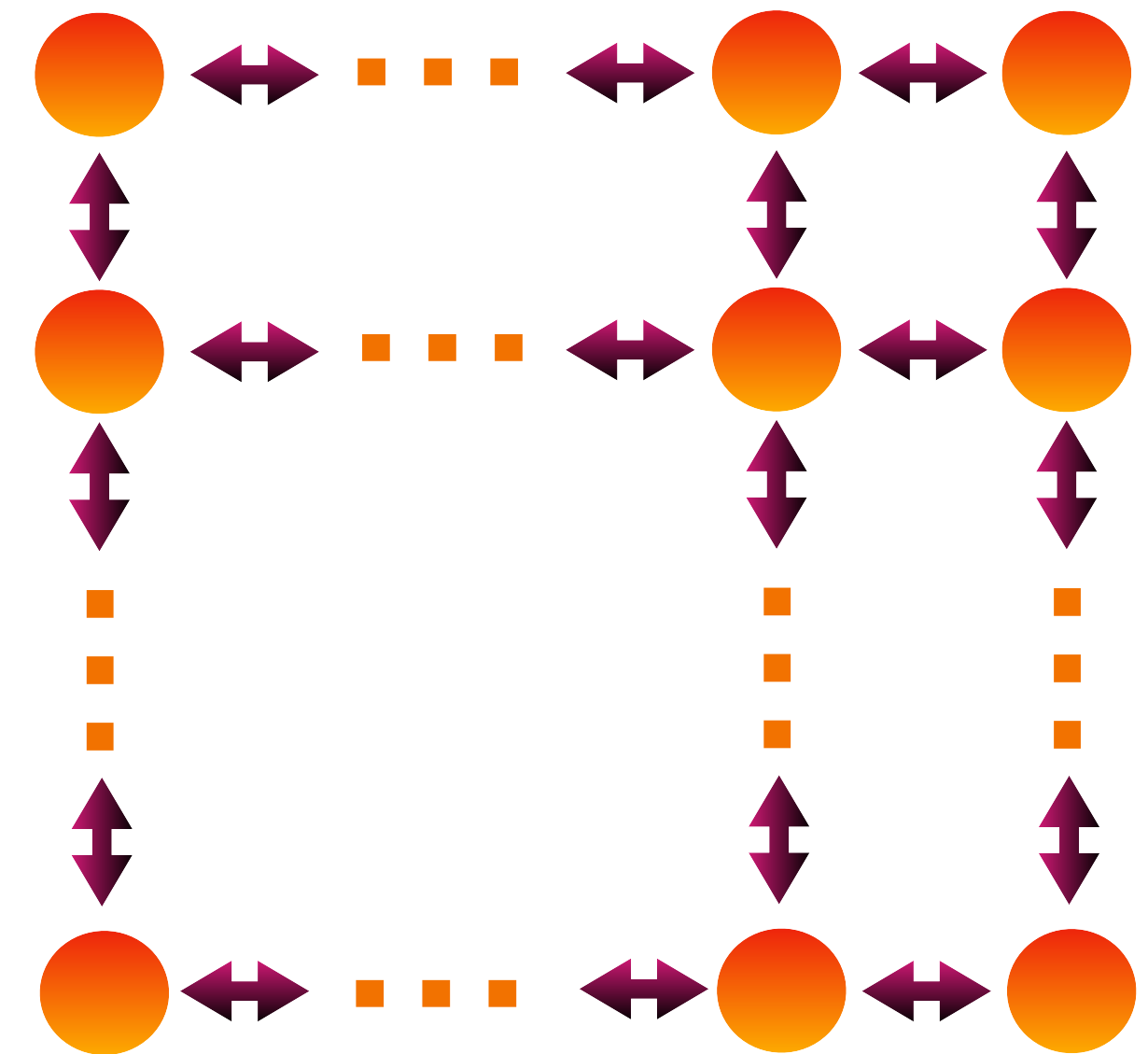


$$D = O\left(\frac{n^d J(J + E)t^2}{\epsilon_{\text{Trot}}}\right)$$

$$\epsilon \lesssim \frac{\Gamma t}{D} + \frac{\ln(M_{\text{max}}^{(\text{NISQ})})}{2\lambda n D^2}$$



$$\epsilon \lesssim O\left(\frac{\epsilon_{\text{Trot}} \Gamma}{n^d J(J + E)t} + \frac{\epsilon_{\text{Trot}}^2 \ln(M_{\text{max}}^{(\text{NISQ})})}{2\lambda n^{2d+1} J^2 (J + E)^2 t^4}\right)$$



$$\epsilon = \sum_{k=1} \epsilon_k \quad \Gamma = \sum_{k=1} \Gamma_k$$

Conclusion

Noise-assisted simulation

- Applications: NISQ computers and quantum analog simulations.

Conclusion

Noise-assisted simulation

- Applications: NISQ computers and quantum analog simulations.
- The quantum hardware does not need to be changed in order to tune the noise rate;

Conclusion

Noise-assisted simulation

- Applications: NISQ computers and quantum analog simulations.
- The quantum hardware does not need to be changed in order to tune the noise rate;
- Open quantum systems coupled to Markovian environments via stochastic Pauli noise channels with medium- or large-decoherence rates.

Note:

Technique is not restricted only to stochastic Pauli channels

Conclusion

Noise-assisted simulation

- Applications: NISQ computers and quantum analog simulations.
- The quantum hardware does not need to be changed in order to tune the noise rate;
- Open quantum systems coupled to Markovian environments via stochastic Pauli noise channels with medium- or large-decoherence rates.
- Ongoing work: Generalization of this technique to simulate non-perturbative dynamics of open quantum systems.

Thank you for your attention!

José D. Guimarães | 2023

